Appendix B: Traffic Modelling

Sparks Road/Hendersons Road

PHASING SUMMARY

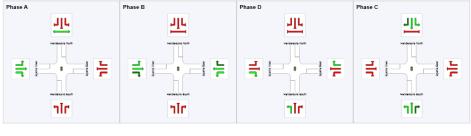
Site: Sparks - Hendersons Option 2015 AM

Sparks - Hendersons Option 2031 AM
Signals - Fixed Time Isolated Cycle Time = 55 seconds (Optimum Cycle Time - Minimum Delay)

Phase times determined by the program Sequence: Split Phasing Movement Class: All Movement Classes Input Sequence: A, B, D, C Output Sequence: A, B, D, C

Phase Timing Results

| Phase | Α | В | D | C |
|-------------------------|------|------|------|------|
| Reference Phase | Yes | No | No | No |
| Phase Change Time (sec) | 0 | 13 | 28 | 41 |
| Green Time (sec) | 7 | 9 | 7 | 8 |
| Yellow Time (sec) | 4 | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 | 2 |
| Phase Time (sec) | 13 | 15 | 13 | 14 |
| Phase Split | 24 % | 27 % | 24 % | 25 % |





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MOVEMENT SUMMARY

Site: Sparks - Hendersons Option 2015 AM

Sparks - Hendersons Option 2031 AM Signals - Fixed Time Isolated Cycle Time = 55 seconds (Optimum Cycle Time - Minimum Delay)

| Movement Per | rformance - Vehicles | | | | | | | | | | |
|------------------|----------------------|----------------|------------|--------------|--------------|----------|------------------|---------------|--------|----------------------|---------------|
| Mov | OD | De | mand Flows | Deg. Satn | Average | Level of | 95% Back of Queu | e | Prop. | Effective | Average |
| ID | Mov | Total veh/h | HV «4 | Satn v/c | Delay sec | Service | Vehicles veh | Distance m | Queued | Stop Rate per veh | Speed km/h |
| South: Henderso | ons South | venni | 76 | V/C | SCC | | veri | "" | | per ven | KIIVII |
| 1 | L2 | 192 | 4.0 | 0.285 | 19.4 | LOS B | 3.6 | 26.4 | 0.73 | 0.77 | 50.2 |
| 2 | T1 | 139 | 4.0 | 0.511 | 25.0 | LOS C | 3.7 | 26.7 | 0.97 | 0.77 | 47.4 |
| 3 | R2 | 11 | 4.0 | 0.081 | 35.1 | LOS D | 0.3 | 2.1 | 0.97 | 0.66 | 40.0 |
| Approach | | 341 | 4.0 | 0.511 | 22.1 | LOS C | 3.7 | 26.7 | 0.84 | 0.76 | 48.6 |
| East: Sparks Eas | st | | | | | | | | | | |
| 4 | L2 | 21 | 4.0 | 0.704 | 32.6 | LOS C | 6.2 | 44.7 | 1.00 | 0.87 | 44.1 |
| 5 | T1 | 199 | 4.0 | 0.704 | 26.2 | LOS C | 6.2 | 44.7 | 1.00 | 0.87 | 48.5 |
| 6 | R2 | 72 | 4.0 | 0.152 | 18.7 | LOS B | 1.3 | 9.4 | 0.78 | 0.73 | 48.7 |
| Approach | | 292 | 4.0 | 0.704 | 24.8 | LOS C | 6.2 | 44.7 | 0.94 | 0.84 | 48.2 |
| North: Henderson | ins North | | | | | | | | | | |
| 7 | L2 | 44 | 4.0 | 0.732 | 34.0 | LOS C | 5.8 | 42.2 | 1.00 | 0.89 | 43.0 |
| 8 | T1 | 158 | 4.0 | 0.732 | 27.6 | LOS C | 5.8 | 42.2 | 1.00 | 0.89 | 45.0 |
| 9 | R2 | 14 | 4.0 | 0.084 | 32.8 | LOS C | 0.4 | 2.6 | 0.94 | 0.68 | 42.4 |
| Approach | | 216 | 4.0 | 0.732 | 29.3 | LOS C | 5.8 | 42.2 | 1.00 | 0.88 | 44.4 |
| West: Sparks We | est | | | | | | | | | | |
| 10 | L2 | 43 | 4.0 | 0.061 | 18.0 | LOS B | 0.7 | 5.2 | 0.64 | 0.71 | 51.7 |
| 11 | T1 | 285 | 4.0 | 0.381 | 13.9 | LOS B | 5.5 | 40.0 | 0.75 | 0.68 | 58.3 |
| 12 | R2 | 487 | 4.0 | 0.722 | 17.0 | LOS B | 7.8 | 56.4 | 0.86 | 0.87 | 52.4 |
| Approach | | 816 | 4.0 | 0.722 | 16.0 | LOS B | 7.8 | 56.4 | 0.81 | 0.79 | 54.2 |
| All Vehicles | | 1664 | 4.0 | 0.732 | 20.5 | LOS C | 7.8 | 56.4 | 0.86 | 0.81 | 50.5 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement interaction and Approach LOS values are based on average delay for all vehicle movements. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. Goga-Acceptance Capacity: SIDRA Standard Chapter (Model Capacity): SIDRA Standard (Alogiel Model).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement Per | formance - Pedestrians | | | | | | | |
|-----------------|------------------------|--------|---------|----------|--------------|-----------------------|--------|-----------|
| Mov | | Demand | Average | Level of | Average Back | Average Back of Queue | | Effective |
| ID | Description | Flow | Delay | Service | Pedestrian | Distance | Queued | Stop Rate |
| | | ped/h | sec | | ped | m | | per ped |
| P3 | North Full Crossing | 53 | 21.9 | LOS C | 0.1 | 0.1 | 0.89 | 0.89 |
| All Pedestrians | | 53 | 21.9 | LOS C | | | 0.89 | 0.89 |

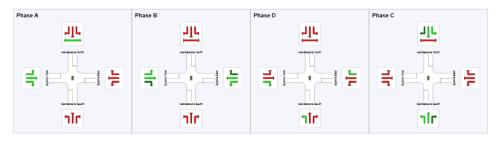
Site: Sparks - Hendersons Option 2015 PM

Sparks - Hendersons Option 2031 AM
Signals - Fixed Time Isolated Cycle Time = 70 seconds (Optimum Cycle Time - Minimum Delay)

Phase times determined by the program Sequence: Split Phasing Movement Class: All Movement Classes Input Sequence: A, B, D, C Output Sequence: A, B, D, C

Phase Timing Results

| Phase | Α | В | D | С |
|-------------------------|------|------|------|------|
| Reference Phase | Yes | No | No | No |
| Phase Change Time (sec) | 0 | 12 | 39 | 51 |
| Green Time (sec) | 6 | 21 | 6 | 13 |
| Yellow Time (sec) | 4 | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 | 2 |
| Phase Time (sec) | 12 | 27 | 12 | 19 |
| Phase Snlit | 17 % | 39 % | 17 % | 27 % |





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MOVEMENT SUMMARY

Site: Sparks - Hendersons Option 2015 PM

| Movement P | erformance - Vehicles | | | | | | | | | | |
|----------------|-----------------------|---------------------|------------------------|---------------------|-------------------------|---------------------|-------------------------------------|--------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | D Total veh/h | emand Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Queu Vehicles veh | e Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| South: Hender | rsons South | VOIDII | | VIC | 300 | | YGII | | | por von | KIIDII |
| 1 | L2 | 313 | 4.0 | 0.498 | 25.7 | LOS C | 8.5 | 61.6 | 0.83 | 0.81 | 46.2 |
| 2 | T1 | 122 | 4.0 | 0.351 | 27.7 | LOS C | 3.8 | 27.3 | 0.91 | 0.73 | 45.7 |
| 3 | R2 | 5 | 4.0 | 0.041 | 40.8 | LOS D | 0.2 | 1.3 | 0.95 | 0.64 | 37.6 |
| Approach | | 440 | 4.0 | 0.498 | 26.4 | LOS C | 8.5 | 61.6 | 0.86 | 0.79 | 46.0 |
| East: Sparks E | ast | | | | | | | | | | |
| 4 | L2 | 32 | 4.0 | 0.780 | 33.5 | LOS C | 12.5 | 90.6 | 0.93 | 0.88 | 43.7 |
| 5 | T1 | 344 | 4.0 | 0.780 | 27.0 | LOS C | 12.5 | 90.6 | 0.93 | 0.88 | 48.0 |
| 6 | R2 | 102 | 4.0 | 0.187 | 18.4 | LOS B | 2.1 | 14.9 | 0.70 | 0.75 | 48.9 |
| Approach | | 478 | 4.0 | 0.780 | 25.6 | LOS C | 12.5 | 90.6 | 0.88 | 0.85 | 47.9 |
| North: Henders | sons North | | | | | | | | | | |
| 7 | L2 | 64 | 4.0 | 0.754 | 38.9 | LOS D | 9.0 | 65.0 | 0.99 | 0.90 | 40.5 |
| 8 | T1 | 189 | 4.0 | 0.754 | 32.5 | LOS C | 9.0 | 65.0 | 0.99 | 0.90 | 42.4 |
| 9 | R2 | 27 | 4.0 | 0.148 | 36.4 | LOS D | 0.9 | 6.3 | 0.91 | 0.72 | 40.7 |
| Approach | | 281 | 4.0 | 0.754 | 34.3 | LOS C | 9.0 | 65.0 | 0.99 | 0.88 | 41.8 |
| West: Sparks V | West | | | | | | | | | | |
| 10 | L2 | 23 | 4.0 | 0.028 | 17.6 | LOS B | 0.4 | 3.0 | 0.56 | 0.69 | 52.0 |
| 11 | T1 | 182 | 4.0 | 0.206 | 12.7 | LOS B | 3.6 | 26.4 | 0.62 | 0.58 | 59.4 |
| 12 | R2 | 345 | 4.0 | 0.615 | 17.0 | LOS B | 5.8 | 42.1 | 0.82 | 0.81 | 52.4 |
| Approach | | 551 | 4.0 | 0.615 | 15.6 | LOS B | 5.8 | 42.1 | 0.74 | 0.73 | 54.5 |
| All Vehicles | | 1749 | 4.0 | 0.780 | 24.1 | LOS C | 12.5 | 90.6 | 0.85 | 0.80 | 48.1 |

Level of Service (LOS) Method: Delay (HCM 2000)

Vehicle movement LOS values are based on average delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements.
SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.
SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.
SIDRA Standard (Akçelik MSO).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement Per | formance - Pedestrians | | | | | | | |
|-----------------|------------------------|--------|---------|----------|-----------------------|----------|--------|-----------|
| Mov | | Demand | Average | Level of | Average Back of Queue | | Prop. | Effective |
| ID | Description | Flow | Delay | Service | Pedestrian | Distance | Queued | Stop Rate |
| | | ped/h | sec | | ped | m | | per ped |
| P3 | North Full Crossing | 53 | 29.3 | LOS C | 0.1 | 0.1 | 0.92 | 0.92 |
| All Pedestrians | | 53 | 29.3 | LOS C | | | 0.92 | 0.92 |

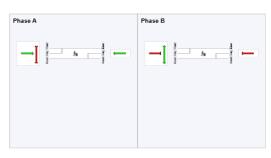
Sparks Road midblock near Rydal Street

PHASING SUMMARY

★ Site: Hoon Hay School Midblock AM

Phase times specified by the user Sequence: Two-Phase Movement Class: All Movement Classes Input Sequence: A, B Output Sequence: A, B

Phase Timing Results Phase
Phase
Reference Phase
Phase Change Time (sec) No 40 14 4 Green Time (sec) Yellow Time (sec) All-Red Time (sec) Phase Time (sec)
Phase Split





MOVEMENT SUMMARY

Site: Hoon Hay School Midblock AM

New Site

Pedestrian Crossing (Signals) - Fixed Time Isolated Cycle Time = 60 seconds (User-Given Phase Times)

| Moveme | ent Performa | nce - Vehicles | ; | | | | | | | | |
|------------|--------------|-------------------------|--------------------|---------------------|-------------------------|---------------------|--------------------------------|--------------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | Deman Total veh/h | d Flows H∨ % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Vehicles veh | f Queue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| East: Ho | on Hay East | | | | | | | | | | |
| 8 | T1 | 319 | 5.0 | 0.287 | 7.3 | LOSA | 4.8 | 35.3 | 0.55 | 0.47 | 43.6 |
| Approach | 1 | 319 | 5.0 | 0.287 | 7.3 | LOS A | 4.8 | 35.3 | 0.55 | 0.47 | 43.6 |
| West: Ho | on Hay West | | | | | | | | | | |
| 2 | T1 | 753 | 1.4 | 0.663 | 9.8 | LOSA | 15.4 | 109.1 | 0.75 | 0.67 | 41.7 |
| Approach | 1 | 753 | 1.4 | 0.663 | 9.8 | LOS A | 15.4 | 109.1 | 0.75 | 0.67 | 41.7 |
| All Vehicl | les | 1072 | 2.5 | 0.663 | 9.0 | LOS A | 15.4 | 109.1 | 0.69 | 0.61 | 42.3 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap-Acceptance Capacity: SIDRA Standard (Akçelik M3D).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

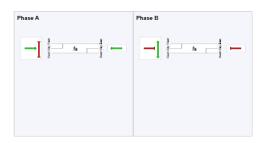
| Movem | ent Performance - Pedestrians | | | | | | | |
|----------|-------------------------------|--------|---|---------|------------|-----------|--------|-----------|
| Mov | | Demand | Demand Average Level of Average Back of Queue | | Prop. | Effective | | |
| ID | Description | Flow | Delay | Service | Pedestrian | Distance | Queued | Stop Rate |
| | | ped/h | sec | | ped | m | | per ped |
| P1 | West Full Crossing | 53 | 24.4 | LOS C | 0.1 | 0.1 | 0.90 | 0.90 |
| All Pede | All Pedestrians | | 24.4 | LOS C | | | 0.90 | 0.90 |

Ŝ Site: Hoon Hay School Midblock PM

New Site
Pedestrian Crossing (Signals) - Fixed Time Isolated Cycle Time = 60 seconds (User-Given Phase Times)

Phase times specified by the user Sequence: Two-Phase Movement Class: All Movement Classes Input Sequence: A, B Output Sequence: A, B

Phase Timing Results Phase
Reference Phase
Phase Change Time (sec)
Green Time (sec)
Yellow Time (sec) All-Red Time (sec) Phase Time (sec) Phase Split





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MOVEMENT SUMMARY

Site: Hoon Hay School Midblock PM

New Site

| Moveme | ent Performa | nce - Vehicles | ; | | | | | | | | |
|---------------------|--------------|-------------------------|--------------------|---------------------|-------------------------|---------------------|--------------------------------|------------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | Deman Total veh/h | d Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Vehicles veh | Queue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| East: Hoon Hay East | | | | | | | | | | | |
| 8 | T1 | 622 | 1.0 | 0.547 | 8.8 | LOSA | 11.5 | 81.1 | 0.67 | 0.60 | 42.4 |
| Approach | | 622 | 1.0 | 0.547 | 8.8 | LOS A | 11.5 | 81.1 | 0.67 | 0.60 | 42.4 |
| West: Ho | on Hay West | | | | | | | | | | |
| 2 | T1 | 595 | 1.9 | 0.526 | 8.7 | LOSA | 10.8 | 76.9 | 0.66 | 0.59 | 42.5 |
| Approach | | 595 | 1.9 | 0.526 | 8.7 | LOS A | 10.8 | 76.9 | 0.66 | 0.59 | 42.5 |
| All Vehicle | es | 1217 | 1.5 | 0.547 | 8.8 | LOS A | 11.5 | 81.1 | 0.67 | 0.59 | 42.5 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. Gap-Acceptance Capacity: SIDRA Standard (Akçelik M3D).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movem | ent Performance - Pedestrians | | | | | | | |
|----------|-------------------------------|--------|---------|----------|--------------|----------|--------|-----------|
| Mov | | Demand | Average | Level of | Average Back | of Queue | Prop. | Effective |
| ID | Description | Flow | Delay | Service | Pedestrian | Distance | Queued | Stop Rate |
| | | ped/h | sec | | ped | m | | per ped |
| P1 | West Full Crossing | 53 | 24.4 | LOS C | 0.1 | 0.1 | 0.90 | 0.90 |
| All Pede | strians | 53 | 24.4 | LOS C | | | 0.90 | 0.90 |

Sparks Road/Hoon Hay Road

PHASING SUMMARY

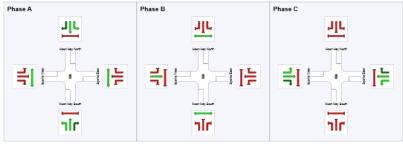
Site: Hoon Hay - Sparks - 2031 AM On road cycle protection - East Only Phase

Hoon Hay - Sparks - 2031 PM Signals - Fixed Time Isolated Cycle Time = 50 seconds (Optimum Cycle Time - Minimum Delay)

Phase times determined by the program Sequence: Split Phasing Movement Class: All Movement Classes Input Sequence: A, B, C Output Sequence: A, B, C

Phase Timing Results

| Phase | Α | В | С |
|-------------------------|------|------|------|
| Reference Phase | Yes | No | No |
| Phase Change Time (sec) | 0 | 20 | 31 |
| Green Time (sec) | 14 | 5 | 13 |
| Yellow Time (sec) | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 |
| Phase Time (sec) | 20 | 11 | 19 |
| Phase Split | 40 % | 22 % | 38 % |





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MOVEMENT SUMMARY

₿ Site: Hoon Hay - Sparks - 2031 AM On road cycle protection - East Only Phase Hoon Hay - Sparks - 2031 PM Signals - Fixed Time Isolated Cycle Time = 50 seconds (Optimum Cycle Time - Minimum Delay)

| Movement Pe | erformance - Vehicle | es | | | | | | | | | |
|-----------------|----------------------|-----------------------|-----------------------|---------------------|-------------------------|---------------------|------------------------------------|----------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | Der Total veh/h | nand Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Que Vehicles veh | eue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| South: Hoon Ha | sy South | | | | | | | | | | |
| 1 | L2 | 2 | 0.0 | 0.866 | 31.4 | LOS C | 13.9 | 99.3 | 1.00 | 1.12 | 36.3 |
| 2 | T1 | 467 | 2.7 | 0.866 | 26.8 | LOS C | 13.9 | 99.3 | 1.00 | 1.12 | 36.6 |
| 3 | R2 | 17 | 0.0 | 0.079 | 27.0 | LOS C | 0.4 | 2.7 | 0.92 | 0.68 | 36.2 |
| Approach | | 486 | 2.6 | 0.866 | 26.9 | LOS C | 13.9 | 99.3 | 1.00 | 1.10 | 36.5 |
| East: Sparks Ea | ast | | | | | | | | | | |
| 4 | L2 | 12 | 9.1 | 0.638 | 23.5 | LOS C | 7.4 | 54.5 | 0.94 | 0.82 | 39.3 |
| 5 | T1 | 312 | 5.4 | 0.638 | 18.9 | LOS B | 7.4 | 54.5 | 0.94 | 0.82 | 39.7 |
| 6 | R2 | 89 | 3.5 | 0.411 | 25.2 | LOS C | 2.1 | 15.0 | 0.91 | 0.77 | 36.8 |
| Approach | | 413 | 5.1 | 0.638 | 20.4 | LOS C | 7.4 | 54.5 | 0.93 | 0.81 | 39.0 |
| North: Hoon Ha | y North | | | | | | | | | | |
| 7 | L2 | 109 | 1.9 | 0.658 | 23.0 | LOS C | 8.0 | 58.3 | 0.94 | 0.84 | 39.0 |
| 8 | T1 | 240 | 5.3 | 0.658 | 18.4 | LOS B | 8.0 | 58.3 | 0.94 | 0.84 | 39.3 |
| 9 | R2 | 5 | 0.0 | 0.035 | 30.0 | LOS C | 0.1 | 0.9 | 0.96 | 0.63 | 35.1 |
| Approach | | 355 | 4.2 | 0.658 | 20.0 | LOS B | 8.0 | 58.3 | 0.94 | 0.83 | 39.1 |
| West: Sparks W | Vest | | | | | | | | | | |
| 10 | L2 | 26 | 0.0 | 0.831 | 21.7 | LOS C | 18.8 | 133.3 | 0.88 | 0.94 | 40.1 |
| 11 | T1 | 739 | 1.3 | 0.831 | 17.1 | LOS B | 18.8 | 133.3 | 0.88 | 0.94 | 40.4 |
| 12 | R2 | 84 | 1.3 | 0.402 | 28.4 | LOS C | 2.1 | 14.7 | 0.96 | 0.76 | 35.6 |
| Approach | | 849 | 1.2 | 0.831 | 18.4 | LOS B | 18.8 | 133.3 | 0.89 | 0.92 | 39.9 |
| All Vehicles | | 2103 | 2.8 | 0.866 | 21.0 | LOS C | 18.8 | 133.3 | 0.93 | 0.93 | 38.8 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on everage delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements. SIDRA Standard Delay Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy Mocional Surgard Collegy (Mocional Surgard Col

| Movemen | t Performance - Pedestrians | | | | | | | |
|-------------|-----------------------------|--------|---------|----------|-------------|----------|--------|-----------|
| Mov | | Demand | Average | Level of | Average Bad | | Prop. | Effective |
| ID | Description | Flow | Delay | Service | Pedestrian | Distance | Queued | Stop Rate |
| | | ped/h | sec | | ped | m | | per ped |
| P1 | South Full Crossing | 53 | 19.4 | LOS B | 0.1 | 0.1 | 0.88 | 0.88 |
| P2 | East Full Crossing | 53 | 19.4 | LOS B | 0.1 | 0.1 | 0.88 | 0.88 |
| P3 | North Full Crossing | 53 | 19.4 | LOS B | 0.1 | 0.1 | 0.88 | 0.88 |
| P4 | West Full Crossing | 53 | 19.4 | LOS B | 0.1 | 0.1 | 0.88 | 0.88 |
| All Pedestr | ians | 211 | 19.4 | LOS B | | | 0.88 | 0.88 |

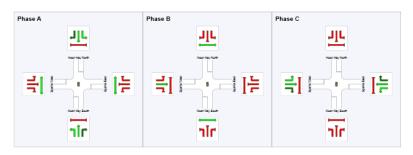
Site: Hoon Hay - Sparks - 2031 PM On road cycle protection - East Only Phase

Hoon Hay - Sparks - 2031 PM
Signals - Fixed Time Isolated Cycle Time = 140 seconds (Optimum Cycle Time - Minimum Delay)

Phase times determined by the program Sequence: Split Phasing Movement Class: All Movement Classes Input Sequence: A, B, C Output Sequence: A, B, C

Phase Timing Results

| r nace rinning recounts | | | |
|-------------------------|-------|---------|-------|
| Phase | Α | В | С |
| Reference Phase | Yes | No | No |
| Phase Change Time (sec) | 0 | 50 | 69 |
| Green Time (sec) | 44 | 13 | 65 |
| Yellow Time (sec) | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 |
| Phase Time (sec) | 50 | 19 | 71 |
| Dhone Split | 26.0/ | 4.4.9/. | E4 0/ |





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MOVEMENT SUMMARY

Site: Hoon Hay - Sparks - 2031 PM On road cycle protection - East Only Phase

| Movement I | Performance - Vehicl | es | | | | | | | | | |
|---------------|----------------------|-----------------------|-----------------------|---------------------|-------------------------|---------------------|------------------------------------|----------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | Der Total veh/h | mand Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Que Vehicles veh | eue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| South: Hoon | Hay South | | | | | | | | | | |
| 1 | L2 | 9 | 0.0 | 0.537 | 46.7 | LOS D | 17.7 | 128.3 | 0.88 | 0.76 | 31.5 |
| 2 | T1 | 308 | 4.1 | 0.537 | 42.2 | LOS D | 17.7 | 128.3 | 0.88 | 0.76 | 31.7 |
| 3 | R2 | 13 | 0.0 | 0.231 | 82.8 | LOS F | 0.9 | 6.4 | 1.00 | 0.66 | 23.3 |
| Approach | | 331 | 3.8 | 0.537 | 43.9 | LOS D | 17.7 | 128.3 | 0.88 | 0.75 | 31.2 |
| East: Sparks | East | | | | | | | | | | |
| 4 | L2 | 22 | 0.0 | 1.014 | 123.6 | LOS F | 72.7 | 513.4 | 1.00 | 1.30 | 18.9 |
| 5 | T1 | 678 | 1.1 | 1.014 | 119.0 | LOS F | 72.7 | 513.4 | 1.00 | 1.30 | 19.0 |
| 6 | R2 | 144 | 0.7 | 0.383 | 31.2 | LOS C | 6.5 | 45.7 | 0.69 | 0.76 | 34.7 |
| Approach | | 844 | 1.0 | 1.014 | 104.1 | LOS F | 72.7 | 513.4 | 0.95 | 1.20 | 20.6 |
| North: Hoon I | Hay North | | | | | | | | | | |
| 7 | L2 | 148 | 1.4 | 0.999 | 104.9 | LOS F | 55.5 | 394.8 | 1.00 | 1.23 | 20.8 |
| 8 | T1 | 434 | 1.9 | 0.999 | 100.3 | LOS F | 55.5 | 394.8 | 1.00 | 1.23 | 20.9 |
| 9 | R2 | 21 | 0.0 | 0.099 | 57.1 | LOS E | 1.2 | 8.5 | 0.87 | 0.71 | 27.9 |
| Approach | | 603 | 1.7 | 0.999 | 99.9 | LOS F | 55.5 | 394.8 | 1.00 | 1.21 | 21.1 |
| West: Sparks | West | | | | | | | | | | |
| 10 | L2 | 13 | 0.0 | 0.441 | 20.5 | LOS C | 19.8 | 140.9 | 0.58 | 0.53 | 40.7 |
| 11 | T1 | 536 | 2.0 | 0.441 | 15.9 | LOS B | 19.8 | 140.9 | 0.58 | 0.53 | 41.0 |
| 12 | R2 | 8 | 0.0 | 0.149 | 82.0 | LOS F | 0.6 | 4.2 | 1.00 | 0.65 | 23.4 |
| Approach | | 557 | 1.9 | 0.441 | 17.0 | LOS B | 19.8 | 140.9 | 0.59 | 0.53 | 40.5 |
| All Vehicles | | 2335 | 1.8 | 1.014 | 73.7 | LOS E | 72.7 | 513.4 | 0.87 | 0.98 | 24.8 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement
Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap-Acceptance Capacity'. SIDRA Standard (Age, High MSD).

HY (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movemen | nt Performance - Pedestrians | Movement Performance - Pedestrians | | | | | | | | | | | |
|------------|------------------------------|------------------------------------|---------|----------|-------------|----------|--------|-----------|--|--|--|--|--|
| Mov | Description | Demand | Average | Level of | Average Bac | | Prop. | Effective | | | | | |
| ID | Description | Flow | Delay | Service | Pedestrian | Distance | Queued | Stop Rate | | | | | |
| | | ped/h | sec | | ped | m . | | per ped | | | | | |
| P1 | South Full Crossing | 53 | 64.3 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 | | | | | |
| P2 | East Full Crossing | 53 | 40.2 | LOS E | 0.2 | 0.2 | 0.76 | 0.76 | | | | | |
| P3 | North Full Crossing | 53 | 64.3 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 | | | | | |
| P4 | West Full Crossing | 53 | 40.2 | LOS E | 0.2 | 0.2 | 0.76 | 0.76 | | | | | |
| All Pedest | ians | 211 | 52.2 | LOS E | | | 0.86 | 0.86 | | | | | |

Sparks Road/Frankleigh Street/Lyttelton Street

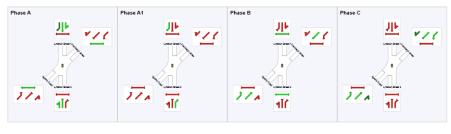
PHASING SUMMARY

Site: Sparks-Lyttelton Base 2031 AM - off road with protected RT

New Site Signals - Fixed Time Isolated Cycle Time = 100 seconds (Practical Cycle Time)

Phase times determined by the program Sequence: Two-Phase Movement Class: All Movement Classes Input Sequence: A, A1, B, C Output Sequence: A, A1, B, C

| Phase Timing Results | | | | | |
|-------------------------|-------|-------|-------|-------|--|
| Phase | Α | A1 | В | С | |
| Reference Phase | Yes | No | No | No | |
| Phase Change Time (sec) | 0 | 34 | 46 | 71 | |
| Green Time (sec) | 28 | 6 | 19 | 23 | |
| Yellow Time (sec) | 4 | 4 | 4 | 4 | |
| All-Red Time (sec) | 2 | 2 | 2 | 2 | |
| Phase Time (sec) | 34 | 12 | 25 | 29 | |
| Dhace Snlit | 3.4 % | 12.96 | 25.94 | 20.96 | |





The results of iterative calculations indicate a somewhat unstable solution. See the Diagnostics section in the Detailed Output report.

SIDRA INTERSECTION 6.1 | Copyright © 2000-2015 Akcelik and Associates Pty Ltd | sidrasolutions.com Organisation: ECCA LIMITED | Processet: Morday 3 October 2016 12:16:16 g.m. Project: X:1200 Quarrymans TransiVioring/SIDRASparks-Lytetion - Final.sp0

MOVEMENT SUMMARY

Site: Sparks-Lyttelton Base 2031 AM - off road with protected RT

| Mov | OD | Don | nand Flows | Deg. | Average | Level of | 95% Back of Qu | 10110 | Prop. | Effective | Average |
|-----------------|------------------|-------|------------|-------|---------|----------|----------------|----------|--------|-----------|---------|
| ID | Mov | Total | HV | Satn | Delay | Service | Vehicles | Distance | Queued | Stop Rate | Speed |
| | | veh/h | % | v/c | sec | | veh | m | | per veh | km/t |
| South: Lyttelt | on Street South | | | | | | | | | | |
| 1b | L3 | 26 | 8.0 | 0.865 | 50.8 | LOS D | 23.0 | 163.0 | 0.99 | 1.03 | 30.6 |
| 2 | T1 | 409 | 1.3 | 0.865 | 45.4 | LOS D | 23.0 | 163.0 | 0.99 | 1.03 | 30.7 |
| 3a | R1 | 48 | 2.2 | 0.440 | 55.9 | LOS E | 2.5 | 17.5 | 1.00 | 0.74 | 28.4 |
| Approach | | 484 | 1.7 | 0.865 | 46.7 | LOS D | 23.0 | 163.0 | 0.99 | 1.00 | 30.5 |
| NorthEast: Fr | rankleigh Street | | | | | | | | | | |
| 24a | L1 | 12 | 9.1 | 0.389 | 21.5 | LOS C | 11.2 | 81.5 | 0.68 | 0.59 | 39.7 |
| 25 | T1 | 355 | 4.7 | 0.389 | 17.5 | LOS B | 11.2 | 81.5 | 0.68 | 0.59 | 40.2 |
| 26b | R3 | 14 | 0.0 | 0.108 | 48.1 | LOS D | 0.6 | 4.3 | 0.90 | 0.71 | 29.9 |
| Approach | | 380 | 4.7 | 0.389 | 18.7 | LOS B | 11.2 | 81.5 | 0.68 | 0.60 | 39.7 |
| North: Lyttelto | on Street North | | | | | | | | | | |
| 7b | L3 | 1 | 0.0 | 0.212 | 35.1 | LOS D | 4.3 | 30.7 | 0.81 | 0.65 | 35.4 |
| 8 | T1 | 114 | 2.8 | 0.212 | 29.7 | LOS C | 4.3 | 30.7 | 0.81 | 0.65 | 35.5 |
| 9a | R1 | 31 | 3.4 | 0.139 | 42.1 | LOS D | 1.3 | 9.5 | 0.92 | 0.70 | 31.7 |
| Approach | | 145 | 2.9 | 0.212 | 32.4 | LOS C | 4.3 | 30.7 | 0.83 | 0.66 | 34.6 |
| SouthWest: S | Sparks Road | | | | | | | | | | |
| 30a | L1 | 81 | 1.3 | 0.895 | 39.8 | LOS D | 42.2 | 298.4 | 0.94 | 0.98 | 33.0 |
| 31 | T1 | 742 | 1.3 | 0.895 | 35.9 | LOS D | 42.2 | 298.4 | 0.94 | 0.98 | 33.4 |
| 32b | R3 | 43 | 2.4 | 0.164 | 39.4 | LOS D | 1.7 | 12.4 | 0.84 | 0.74 | 32.2 |
| Approach | | 866 | 1.3 | 0.895 | 36.4 | LOS D | 42.2 | 298.4 | 0.93 | 0.97 | 33.3 |
| All Vehicles | | 1876 | 2.2 | 0.895 | 35.2 | LOS D | 42.2 | 298.4 | 0.89 | 0.88 | 33.7 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement
Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap-Acceptance Capacity; SIDRA Astndard (Akçelik M3D).

HV (%) values are calculated of all Movement Classes of All Heavy Vehicle Model Designation.

The results of iterative calculations indicate a somewhat unstable solution. See the Diagnostics section in the Detailed Output report.

| Movement | Performance - Pedestrians | | | | | | | |
|---------------|---------------------------|-------------------------|-------------------------|---------------------|-----------------------------------|-----------------------------|-----------------|-----------------------------------|
| Mov ID | Description | Demand Flow ped/h | Average Delay sec | Level of Service | Average Bacl Pedestrian ped | k of Queue Distance m | Prop. Queued | Effective Stop Rate per ped |
| P1 | South Full Crossing | 53 | 44.3 | LOS E | 0.1 | 0.1 | 0.94 | 0.94 |
| P6 | NorthEast Full Crossing | 53 | 33.7 | LOS D | 0.1 | 0.1 | 0.82 | 0.82 |
| P3 | North Full Crossing | 53 | 44.3 | LOS E | 0.1 | 0.1 | 0.94 | 0.94 |
| P8 | SouthWest Full Crossing | 53 | 37.1 | LOS D | 0.1 | 0.1 | 0.86 | 0.86 |
| All Pedestria | All Pedestrians | | 39.8 | LOS D | | | 0.89 | 0.89 |

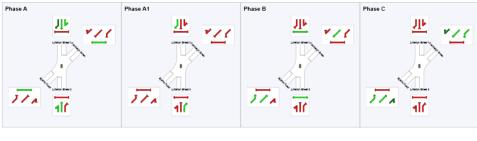
Site: Sparks-Lyttelton Base 2031 PM - off road with protected RT

New Site Signals - Fixed Time Isolated Cycle Time = 120 seconds (Practical Cycle Time)

Phase times determined by the program Sequence: Two-Phase Movement Class: All Movement Classes Input Sequence: A, A1, B, C Output Sequence: A, A1, B, C

Phase Timing Results

| Phase | Α | A1 | В | С |
|-------------------------|-------|-------|-------|-------|
| Reference Phase | Yes | No | No | No |
| Phase Change Time (sec) | 0 | 47 | 59 | 85 |
| Green Time (sec) | 41 | 6 | 20 | 29 |
| Yellow Time (sec) | 4 | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 | 2 |
| Phase Time (sec) | 47 | 12 | 26 | 35 |
| Dhoop Colit | 20.9/ | 10.9/ | 22.0/ | 20.9/ |





The results of iterative calculations indicate a somewhat unstable solution. See the Diagnostics section in the Detailed Output report.

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MOVEMENT SUMMARY

Site: Sparks-Lyttelton Base 2031 PM - off road with protected RT

| Movement F | Performance - Veh | icles | | | | | | | | | |
|-----------------|-------------------|----------------|------------|--------------|--------------|----------|-----------------|---------------|--------|----------------------|---------------|
| Mov | OD | | nand Flows | Deg. Satn | Average | Level of | 95% Back of Qu | | Prop. | Effective | Average |
| ID | Mov | Total veh/h | H∨ % | Satn v/c | Delay sec | Service | Vehicles veh | Distance m | Queued | Stop Rate per veh | Speed km/h |
| South: Lyttelto | on Street South | *61011 | ,, | */- | 300 | | ¥011 | | | por ven | 1411111 |
| 1b | L3 | 36 | 2.9 | 0.537 | 38.9 | LOS D | 14.8 | 104.4 | 0.84 | 0.73 | 34.0 |
| 2 | T1 | 284 | 1.1 | 0.537 | 33.5 | LOS C | 14.8 | 104.4 | 0.84 | 0.73 | 34.1 |
| 3a | R1 | 41 | 2.6 | 0.449 | 67.4 | LOS E | 2.5 | 18.0 | 1.00 | 0.73 | 26.0 |
| Approach | | 361 | 1.5 | 0.537 | 37.9 | LOS D | 14.8 | 104.4 | 0.86 | 0.73 | 32.9 |
| NorthEast: Fra | ankleigh Street | | | | | | | | | | |
| 24a | L1 | 57 | 1.9 | 0.815 | 34.6 | LOS C | 39.7 | 280.7 | 0.93 | 0.86 | 34.7 |
| 25 | T1 | 727 | 1.0 | 0.815 | 30.6 | LOS C | 39.7 | 280.7 | 0.93 | 0.86 | 35.1 |
| 26b | R3 | 1 | 0.0 | 0.006 | 46.1 | LOS D | 0.0 | 0.3 | 0.81 | 0.62 | 30.4 |
| Approach | | 785 | 1,1 | 0.815 | 30.9 | LOS C | 39.7 | 280.7 | 0.93 | 0.86 | 35.1 |
| North: Lyttelto | n Street North | | | | | | | | | | |
| 7b | L3 | 36 | 0.0 | 0.879 | 54.4 | LOS D | 30.0 | 211.0 | 0.95 | 0.98 | 29.8 |
| 8 | T1 | 460 | 0.7 | 0.879 | 49.0 | LOS D | 30.0 | 211.0 | 0.95 | 0.98 | 29.8 |
| 9a | R1 | 81 | 1.3 | 0.238 | 36.9 | LOS D | 3.6 | 25.4 | 0.83 | 0.73 | 33.2 |
| Approach | | 577 | 0.7 | 0.879 | 47.6 | LOS D | 30.0 | 211.0 | 0.93 | 0.95 | 30.2 |
| SouthWest: S | parks Road | | | | | | | | | | |
| 30a | L1 | 138 | 1.5 | 0.780 | 31.6 | LOS C | 30.4 | 216.4 | 0.86 | 0.79 | 35.5 |
| 31 | T1 | 520 | 1.8 | 0.780 | 27.7 | LOS C | 30.4 | 216.4 | 0.86 | 0.79 | 35.9 |
| 32b | R3 | 38 | 2.8 | 0.316 | 58.4 | LOS E | 2.1 | 15.2 | 0.94 | 0.76 | 27.6 |
| Approach | | 696 | 1.8 | 0.780 | 30.1 | LOS C | 30.4 | 216.4 | 0.87 | 0.79 | 35.3 |
| All Vehicles | | 2419 | 1.3 | 0.879 | 35.7 | LOS D | 39.7 | 280.7 | 0.90 | 0.84 | 33.5 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement
Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap-Acceptance Capacity: SIDRA Standard (Akçelik M3D).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

The results of iterative calculations indicate a somewhat unstable solution. See the Diagnostics section in the Detailed Output report.

| Movement Performance - Pedestrians | | | | | | | | | | | |
|------------------------------------|-------------------------|-------------------------|-------------------------|---------------------|----------------------------------|-----------------------------|-----------------|-----------------------------------|--|--|--|
| Mov ID | Description | Demand Flow ped/h | Average Delay sec | Level of Service | Average Bad Pedestrian ped | k of Queue Distance m | Prop. Queued | Effective Stop Rate per ped | | | |
| P1 | South Full Crossing | 53 | 54.3 | LOS E | 0.2 | 0.2 | 0.95 | 0.95 | | | |
| P6 | NorthEast Full Crossing | 53 | 33.1 | LOS D | 0.1 | 0.1 | 0.74 | 0.74 | | | |
| P3 | North Full Crossing | 53 | 54.3 | LOS E | 0.2 | 0.2 | 0.95 | 0.95 | | | |
| P8 | SouthWest Full Crossing | 53 | 36.1 | LOS D | 0.1 | 0.1 | 0.78 | 0.78 | | | |
| All Pedestr | rians | 211 | 44.4 | LOS E | | | 0.86 | 0.86 | | | |

Strickland Street at Roker Street

PHASING SUMMARY

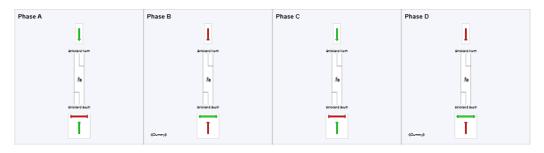
Site: Strickland Street Midblock 2031 AM

Strickland Street Midblock
Pedestrian Crossing (Signals) - Fixed Time Coordinated Cycle Time = 100 seconds (Network Cycle Time)

Phase times determined by the program Sequence: Two-Phase Movement Class: All Movement Classes Input Sequence: A, B, C, D
Output Sequence: A, B, C, D

Phase Timing Results

| i iluse illilling itesuits | | | | |
|----------------------------|------|------|------|------|
| Phase | Α | В | С | D |
| Reference Phase | Yes | No | No | No |
| Phase Change Time (sec) | 0 | 32 | 42 | 88 |
| Green Time (sec) | 26 | 4 | 40 | 6 |
| Yellow Time (sec) | 4 | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 | 2 |
| Phase Time (sec) | 32 | 10 | 46 | 12 |
| Phase Snlit | 32 % | 10 % | 46 % | 12 % |





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MOVEMENT SUMMARY

Ś∄ Site: Strickland Street Midblock 2031 AM

Strickland Street Midblock
Pedestrian Crossing (Signals) - Fixed Time Coordinated Cycle Time = 100 seconds (Network Cycle Time)

ΦΦ Network: Strickland and Milton 2031 AM

| Movement P | erformance - Vehicle | s | | | | | | | | | | | |
|-----------------|----------------------|------------|-------------------|-------|---------------------|--------------|------------------|---------------------|---------------------------|------------------|-----------------|------------------------|------------------|
| Mov ID | OD Mov | D Total | emand Flows HV | Total | Arrival Flows HV | Deg. Satn | Average Delay | Level of Service | 95% Back of Q Vehicles | ueue Distance | Prop. Queued | Effective Stop Rate | Average Speed |
| | | veh/h | % | veh/h | % | v/c | sec | | veh | m | | per veh | km/h |
| South: Strickla | ind South | | | | | | | | | | | | |
| 2 | T1 | 572 | 1.8 | 572 | 1.8 | 0.899 | 31.7 | LOS C | 22.7 | 161.2 | 0.90 | 1.01 | 26.8 |
| Approach | | 572 | 1.8 | 572 | 1.8 | 0.899 | 31.7 | LOS C | 22.7 | 161.2 | 0.90 | 1.01 | 26.8 |
| North: Strickla | nd North | | | | | | | | | | | | |
| 8 | T1 | 148 | 2.8 | 148 | 2.8 | 0.117 | 1.9 | LOS A | 0.7 | 5.0 | 0.19 | 0.16 | 47.8 |
| Approach | | 148 | 2.8 | 148 | 2.8 | 0.117 | 1.9 | LOS A | 0.7 | 5.0 | 0.19 | 0.16 | 47.8 |
| All Vehicles | | 720 | 2.0 | 720 | 2.0 | 0.899 | 25.6 | LOS C | 22.7 | 161.2 | 0.75 | 0.83 | 29.7 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on sverage delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. Gap-Acceptance Capaperty, SIDRA Standard (Aplaçaik Model).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement Per | rformance - Pedestrians | | | | | | | |
|-----------------|-------------------------|----------------|------------------|---------------------|----------------------------|----------------------|-----------------|------------------------|
| Mov | Description | Demand Flow | Average Delay | Level of Service | Average Baci Pedestrian | of Queue Distance | Prop. Queued | Effective Stop Rate |
| ID . | | ped/h | Sec Sec | Service | ped | Distance m | Queuea | per ped |
| P1 | South Full Crossing | 53 | 20.0 | LOS C | 0.1 | 0.1 | 0.88 | 0.88 |
| All Pedestrians | | 53 | 20.0 | LOS C | | | 0.88 | 0.88 |

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movement.

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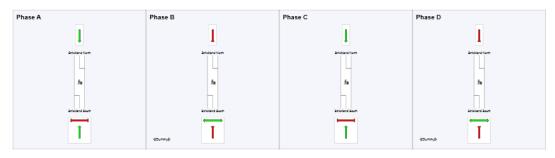
Ś∄ Site: Strickland Street Midblock 2031 PM

Strickland Street Midblock

Phase times determined by the program Sequence: Two-Phase Movement Class: All Movement Classes Input Sequence: A, B, C, D Output Sequence: A, B, C, D

Phase Timing Results

| Phase | Α | В | С | D |
|-------------------------|------|------|------|------|
| Reference Phase | Yes | No | No | No |
| Phase Change Time (sec) | 0 | 32 | 43 | 89 |
| Green Time (sec) | 26 | 5 | 40 | 5 |
| Yellow Time (sec) | 4 | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 | 2 |
| Phase Time (sec) | 32 | 11 | 46 | 11 |
| Phase Split | 32 % | 11 % | 46 % | 11 % |





The results of iterative calculations indicate a somewhat unstable solution. See the Diagnostics section in the Detailed Output report.

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MOVEMENT SUMMARY

Ś∄ Site: Strickland Street Midblock 2031 PM

φφ Network: Strickland and Milton 2031 PM

Strickland Street Midblock
Pedestrian Crossing (Signals) - Fixed Time Coordinated Cycle Time = 100 seconds (Network Cycle Time)

| Movement Pe | erformance - Vehicles | ; | | | | | | | | | | | |
|------------------|-----------------------|--------------|------------------|-------|---------------------|--------------|------------------|---------------------|----------------------------|-----------------|-----------------|------------------------|------------------|
| Mov | OD Mov | Der Total | nand Flows HV | Total | Arrival Flows HV | Deg. Sata | Average Delay | Level of Service | 95% Back of Qu Vehicles | eue Distance | Prop. Queued | Effective Stop Rate | Average Speed |
| | | veh/h | | veh/h | | v/c | sec | | veh | m | | per veh | km/h |
| South: Stricklar | nd South | | | | | | | | | | | | |
| 2 | T1 | 263 | 1.2 | 263 | 1.2 | 0.217 | 3.6 | LOSA | 2.6 | 18.3 | 0.42 | 0.36 | 45.5 |
| Approach | | 263 | 1.2 | 263 | 1.2 | 0.217 | 3.6 | LOS A | 2.6 | 18.3 | 0.42 | 0.36 | 45.5 |
| North: Stricklar | nd North | | | | | | | | | | | | |
| 8 | T1 | 519 | 1.0 | 519 | 1.0 | 0.406 | 4.3 | LOSA | 6.0 | 42.2 | 0.50 | 0.44 | 45.2 |
| Approach | | 519 | 1.0 | 519 | 1.0 | 0.406 | 4.3 | LOS A | 6.0 | 42.2 | 0.50 | 0.44 | 45.2 |
| All Vehicles | | 782 | 1.1 | 782 | 1.1 | 0.406 | 4.1 | LOS A | 6.0 | 42.2 | 0.47 | 0.41 | 45.3 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement intersection and Approach in LOS values are based on average delay for all vehicle movements.

SIGHA Standard Delay Mode is used. Control Delay includes Geometric Delay.

Gap-Acceptance Capacity: SIGRA Standard (Akpeilk M3D).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

The results of iterative calculations indicate a somewhat unstable solution. See the Diagnostics section in the Detailed Output report.

| Movement Per | rformance - Pedestrians | | | | | | | |
|-----------------|-------------------------|-------------------------|-------------------------|---------------------|----------------------------------|-----------------------------|-----------------|-----------------------------------|
| Mov ID | Description | Demand Flow ped/h | Average Delay sec | Level of Service | Average Bac Pedestrian ped | k of Queue Distance m | Prop. Queued | Effective Stop Rate per ped |
| P1 | South Full Crossing | 53 | 19.9 | LOS B | 0.1 | 0.1 | 0.88 | 0.88 |
| All Pedestrians | | 53 | 19.9 | LOS B | | | 0.88 | 0.88 |

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay)
Pedestrian movement LOS values are based on average delay per pedestrian movement.
Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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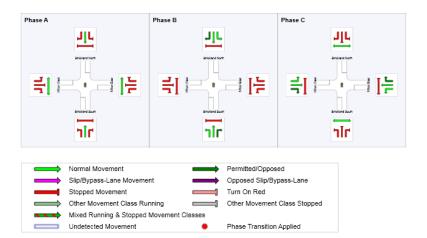
Strickland Street/Milton Street

PHASING SUMMARY

Site: Strickland and Milton 2031 AM

Phase times determined by the program Sequence: Two-Phase
Movement Class: All Movement Classes
Input Sequence: A, B, C
Output Sequence: A, B, C

Phase Timing Results Phase Reference Phase Phase Change Time (sec) Green Time (sec) Yellow Time (sec) All-Red Time (sec) A Yes 0 11 4 2 17 B No 17 29 4 2 35 35 35 % C No 52 42 4 Phase Time (sec) Phase Split



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MOVEMENT SUMMARY

Site: Strickland and Milton 2031 AM

φφ Network: Strickland and Milton 2031 AM

New Site Signals - Fixed Time Coordinated Cycle Time = 100 seconds (Network Cycle Time)

| Movement De | erformance - Vehicle | ve. | | | | | | | | | | | |
|------------------|----------------------|------|-------------------------|----------------|--------------------------|---------------------|-------------------------|---------------------|-----------------------------------|-----------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mav | | Demand Flows HV % | Total veh/h | Arrival Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Qu Vehicles veh | leue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| South: Stricklan | id South | | | | | | | | | | | | |
| 1 | L2 | 1 | 0.0 | 1 | 0.0 | 0.616 | 23.7 | LOS C | 11.5 | 81.6 | 0.75 | 0.66 | 33.2 |
| 2 | T1 | 502 | 1.7 | 502 | 1.7 | 0.616 | 19.9 | LOS B | 11.5 | 81.6 | 0.75 | 0.66 | 33.6 |
| 3 | R2 | 68 | 1.5 | 68 | 1.5 | 0.173 | 32.8 | LOS C | 2.6 | 18.7 | 0.82 | 0.74 | 27.4 |
| Approach | | 572 | 1.7 | 572 | 1.7 | 0.616 | 21.4 | LOS C | 11.5 | 81.6 | 0.76 | 0.67 | 32.7 |
| East: Milton Eas | st | | | | | | | | | | | | |
| 4 | L2 | 25 | 4.2 | 25 | 4.2 | 0.605 | 28.8 | LOS C | 19.1 | 138.4 | 0.83 | 0.74 | 30.1 |
| 5 | T1 | 480 | 4.2 | 480 | 4.2 | 0.605 | 24.2 | LOS C | 19.1 | 138.4 | 0.83 | 0.74 | 37.5 |
| 6 | R2 | 1 | 0.0 | 1 | 0.0 | 0.011 | 53.0 | LOS D | 0.0 | 0.3 | 0.95 | 0.59 | 28.9 |
| Approach | | 506 | 4.2 | 506 | 4.2 | 0.605 | 24.5 | LOS C | 19.1 | 138.4 | 0.83 | 0.74 | 37.2 |
| North: Stricklan | d North | | | | | | | | | | | | |
| 7 | L2 | 4 | 25.0 | 4 | 25.0 | 0.136 | 21.3 | LOS C | 3.5 | 25.4 | 0.61 | 0.50 | 40.2 |
| 8 | T1 | 123 | 2.6 | 123 | 2.6 | 0.136 | 16.5 | LOS B | 3.5 | 25.4 | 0.61 | 0.50 | 34.6 |
| 9 | R2 | 28 | 7.4 | 28 | 7.4 | 0.106 | 33.3 | LOS C | 1.0 | 7.7 | 0.76 | 0.71 | 34.0 |
| Approach | | 156 | 4.1 | 156 | 4.1 | 0.136 | 19.7 | LOS B | 3.5 | 25.4 | 0.64 | 0.54 | 34.6 |
| West: Milton We | est | | | | | | | | | | | | |
| 10 | L2 | 18 | 0.0 | 18 | 0.0 | 0.906 | 47.2 | LOS D | 42.7 | 302.5 | 1.00 | 1.07 | 31.4 |
| 11 | T1 | 749 | 1.4 | 749 | 1.4 | 0.906 | 42.6 | LOS D | 42.7 | 302.5 | 1.00 | 1.07 | 31.5 |
| 12 | R2 | 1 | 0.0 | 1 | 0.0 | 0.005 | 36.6 | LOS D | 0.0 | 0.3 | 0.79 | 0.60 | 25.1 |
| Approach | | 768 | 1.4 | 768 | 1.4 | 0.906 | 42.7 | LOS D | 42.7 | 302.5 | 1.00 | 1.07 | 31.5 |
| All Vehicles | | 2002 | 2.4 | 2002 | 2.4 | 0.906 | 30.2 | LOS C | 42.7 | 302.5 | 0.86 | 0.83 | 33.4 |

Level of Service (LOS) Method: Delsy (HCM 2000).

Vehicle movement LOS values are based on average delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. Gap-Acceptance Orgapecty, SIDRA Standard (Aspletik Model).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

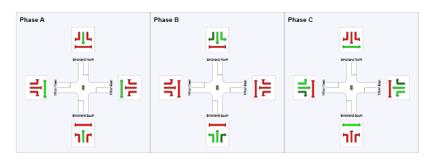
| Movement Performance - Pedestrians | | | | | | | | | | |
|------------------------------------|---------------------|--------|---------|----------|-------------|----------|--------|-----------|--|--|
| Mov | | Demand | Average | Level of | Average Bac | | Prop. | Effective | | |
| ID | Description | Flow | Delay | Service | Pedestrian | Distance | Queued | Stop Rate | | |
| | | ped/h | sec | | ped | m | | per ped | | |
| P1 | South Full Crossing | 53 | 23.2 | LOS C | 0.1 | 0.1 | 0.68 | 0.68 | | |
| P2 | East Full Crossing | 53 | 44.3 | LOS E | 0.1 | 0.1 | 0.94 | 0.94 | | |
| P3 | North Full Crossing | 53 | 23.2 | LOS C | 0.1 | 0.1 | 0.68 | 0.68 | | |
| P4 | West Full Crossing | 53 | 44.3 | LOS E | 0.1 | 0.1 | 0.94 | 0.94 | | |
| All Pedestria | ns | 211 | 33.7 | LOS D | | | 0.81 | 0.81 | | |

Site: Strickland and Milton 2031 PM

Phase times determined by the program Sequence: Two-Phase
Movement Class: All Movement Classes
Input Sequence: A, B, C
Output Sequence: A, B, C

Phase Timing Results

| Phase | Α | В | С |
|-------------------------|------|------|------|
| Reference Phase | Yes | No | No |
| Phase Change Time (sec) | 0 | 17 | 46 |
| Green Time (sec) | 11 | 23 | 48 |
| Yellow Time (sec) | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 |
| Phase Time (sec) | 17 | 29 | 54 |
| Phase Split | 17 % | 29 % | 54 % |





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MOVEMENT SUMMARY

Site: Strickland and Milton 2031 PM

 $\varphi\varphi$ Network: Strickland and Milton 2031 PM

New Site Signals - Fixed Time Coordinated Cycle Time = 100 seconds (Network Cycle Time)

| Movement P | erformance - Vehic | les | | | | | | | | | | | |
|------------------|--------------------|----------------------|------------------------|----------------|--------------------------|---------------------|-------------------------|---------------------|-----------------------------------|----------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | De Total veh/h | emand Flows HV % | Total veh/h | Arrival Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Qu Vehicles veh | eue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| South: Strickla | nd South | VCIVII | ~ | VEIDII | 76 | VIC | 200 | | Veli | "" | | per veri | KIIDII |
| 1 | L2 | 1 | 0.0 | 1 | 0.0 | 0.311 | 25.6 | LOS C | 7.1 | 50.0 | 0.66 | 0.56 | 32.2 |
| 2 | T1 | 234 | 1.4 | 234 | 1.4 | 0.311 | 21.7 | LOS C | 7.1 | 50.0 | 0.66 | 0.56 | 32.6 |
| 3 | R2 | 29 | 0.0 | 29 | 0.0 | 0.122 | 37.6 | LOS D | 1.2 | 8.7 | 0.87 | 0.72 | 25.7 |
| Approach | | 264 | 1.2 | 264 | 1.2 | 0.311 | 23.5 | LOS C | 7.1 | 50.0 | 0.68 | 0.57 | 31.7 |
| East: Milton Ea | ast | | | | | | | | | | | | |
| 4 | L2 | 64 | 1.6 | 64 | 1.6 | 0.832 | 31.9 | LOS C | 36.2 | 255.8 | 0.93 | 0.89 | 28.6 |
| 5 | T1 | 743 | 1.1 | 743 | 1.1 | 0.832 | 27.3 | LOS C | 36.2 | 255.8 | 0.93 | 0.89 | 36.3 |
| 6 | R2 | 1 | 0.0 | 1 | 0.0 | 0.007 | 42.5 | LOS D | 0.0 | 0.3 | 0.85 | 0.60 | 31.5 |
| Approach | | 808 | 1.2 | 808 | 1.2 | 0.832 | 27.7 | LOS C | 36.2 | 255.8 | 0.93 | 0.89 | 35.8 |
| North: Stricklan | nd North | | | | | | | | | | | | |
| 7 | L2 | 11 | 10.0 | 11 | 10.0 | 0.797 | 33.7 | LOS C | 19.2 | 135.5 | 0.83 | 0.80 | 35.4 |
| 8 | T1 | 455 | 0.9 | 455 | 0.9 | 0.797 | 29.1 | LOS C | 19.2 | 135.5 | 0.83 | 0.80 | 28.0 |
| 9 | R2 | 174 | 0.6 | 174 | 0.6 | 0.601 | 42.7 | LOS D | 7.8 | 54.9 | 0.94 | 0.81 | 31.3 |
| Approach | | 639 | 1.0 | 639 | 1.0 | 0.797 | 32.9 | LOS C | 19.2 | 135.5 | 0.86 | 0.80 | 29.4 |
| West: Milton W | /est | | | | | | | | | | | | |
| 10 | L2 | 63 | 1.7 | 63 | 1.7 | 0.787 | 28.5 | LOS C | 31.2 | 221.2 | 0.90 | 0.83 | 37.2 |
| 11 | T1 | 695 | 1.7 | 695 | 1.7 | 0.787 | 23.9 | LOS C | 31.2 | 221.2 | 0.90 | 0.83 | 37.5 |
| 12 | R2 | 1 | 0.0 | 1 | 0.0 | 0.008 | 45.5 | LOS D | 0.0 | 0.3 | 0.88 | 0.60 | 22.4 |
| Approach | | 759 | 1.7 | 759 | 1.7 | 0.787 | 24.3 | LOS C | 31.2 | 221.2 | 0.90 | 0.83 | 37.5 |
| All Vehicles | | 2471 | 1.3 | 2471 | 1.3 | 0.832 | 27.5 | LOSC | 36.2 | 255.8 | 0.88 | 0.82 | 34.6 |

Level of Service (i,O.S) Method: Delay (+ICM 2000).

Vehicle movement, I.O.S values are based on average delay per movement intersection and Approach I.O.S values are based on average delay for all vehicle movements. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. Gap-Acceptance Capacity, SIDRA Standard (Akplick Model).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement Performance - Pedestrians | | | | | | | | | | | |
|------------------------------------|---------------------|-------------------------|-------------------------|---------------------|----------------------------------|-----------------------------|-----------------|-----------------------------------|--|--|--|
| Mov ID | Description | Demand Flow ped/h | Average Delay sec | Level of Service | Average Bac Pedestrian ped | k of Queue Distance m | Prop. Queued | Effective Stop Rate per ped | | | |
| P1 | South Full Crossing | 53 | 19.3 | LOS B | 0.1 | 0.1 | 0.62 | 0.62 | | | |
| P2 | East Full Crossing | 53 | 44.3 | LOS E | 0.1 | 0.1 | 0.94 | 0.94 | | | |
| P3 | North Full Crossing | 53 | 19.3 | LOS B | 0.1 | 0.1 | 0.62 | 0.62 | | | |
| P4 | West Full Crossing | 53 | 44.3 | LOS E | 0.1 | 0.1 | 0.94 | 0.94 | | | |
| All Pedestrian | ns | 211 | 31.8 | LOS D | | | 0.78 | 0.78 | | | |

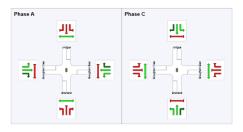
Brougham Street/Strickland Street/Antigua Street base case – no cycleway

PHASING SUMMARY

Site: Antigue-Brougham-Strickland BASE 2031 AM

Phase times determined by the program Sequence: Split Phasing Movement Class: All Movement Classes Input Sequence: A, C Output Sequence: A, C

| Phase Timing Results | | |
|-------------------------|-------|-------|
| Phase | Α | С |
| Reference Phase | Yes | No |
| Phase Change Time (sec) | 0 | 86 |
| Green Time (sec) | 80 | 58 |
| Yellow Time (sec) | 4 | 4 |
| All-Red Time (sec) | 2 | 2 |
| Phase Time (sec) | 86 | 64 |
| Dhone Colit | E7 0/ | 42.0/ |





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MOVEMENT SUMMARY

Site: Antigue-Brougham-Strickland BASE 2031 AM

| Mov | OD | De | emand Flows | Deg. Satn | Average | Level of | 95% Back of Que | | Prop. | Effective | Average |
|-----------------|--------|----------------|-------------|--------------|---------|----------|-----------------|----------|--------|-----------|--------------|
| | Mov | Total veh/h | HV % | | Delay | Service | Vehicles | Distance | Queued | Stop Rate | Speed km/ |
| South: Sricklan | id | ven/n | % | v/c | sec | | veh | m | | per veh | Km/ |
| 1 | L2 | 144 | 4.0 | 1.263 | 333.4 | LOS F | 132.3 | 957.8 | 1.00 | 1.96 | 9.3 |
| 2 | T1 | 617 | 4.0 | 1.263 | 328.8 | LOS F | 132.3 | 957.8 | 1.00 | 1.96 | 9.1 |
| 3 | R2 | 142 | 4.0 | 0.794 | 60.9 | LOS E | 9.5 | 69.1 | 0.85 | 0.89 | 28.3 |
| Approach | | 903 | 4.0 | 1.263 | 287.4 | LOS F | 132.3 | 957.8 | 0.98 | 1.79 | 10.2 |
| East: Broughan | m East | | | | | | | | | | |
| 4 | L2 | 99 | 8.0 | 0.107 | 23.8 | LOS C | 3.5 | 26.1 | 0.52 | 0.70 | 39.9 |
| 5 | T1 | 2200 | 8.0 | 1.153 | 209.8 | LOS F | 166.0 | 1242.0 | 1.00 | 1.72 | 13.5 |
| 6 | R2 | 1 | 8.0 | 0.020 | 86.7 | LOS F | 0.1 | 0.6 | 1.00 | 0.57 | 23.7 |
| Approach | | 2300 | 8.0 | 1.153 | 201.7 | LOS F | 166.0 | 1242.0 | 0.98 | 1.67 | 13.9 |
| North: Antigua | | | | | | | | | | | |
| 7 | L2 | 1 | 4.0 | 0.361 | 38.7 | LOS D | 12.8 | 92.3 | 0.75 | 0.64 | 35.5 |
| 8 | T1 | 252 | 4.0 | 0.361 | 34.1 | LOS C | 12.8 | 92.3 | 0.75 | 0.64 | 34.2 |
| 9 | R2 | 40 | 4.0 | 0.768 | 92.2 | LOS F | 3.2 | 23.4 | 1.00 | 0.82 | 22.8 |
| Approach | | 293 | 4.0 | 0.768 | 42.1 | LOS D | 12.8 | 92.3 | 0.78 | 0.66 | 32.0 |
| West: Brougha | m West | | | | | | | | | | |
| 10 | L2 | 347 | 8.0 | 0.513 | 27.3 | LOS C | 14.6 | 109.2 | 0.63 | 0.76 | 38.5 |
| 11 | T1 | 2125 | 8.0 | 1.246 | 297.9 | LOS F | 205.0 | 1533.4 | 1.00 | 2.01 | 10.2 |
| 12 | R2 | 51 | 8.0 | 0.983 | 111.3 | LOS F | 4.5 | 33.9 | 1.00 | 0.97 | 20.5 |
| Approach | | 2523 | 8.0 | 1.246 | 256.9 | LOS F | 205.0 | 1533.4 | 0.95 | 1.82 | 11.5 |
| All Vehicles | | 6019 | 7.2 | 1.263 | 230.0 | LOS F | 205.0 | 1533.4 | 0.96 | 1.70 | 12.5 |

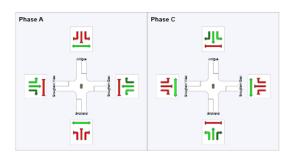
Level of Service (I.O.S) Method: Delay (HCM 2000)
Vehicle movement I.O.S values are based on average delay per movement
Intersection and Approach LOS values are based on average delay for all vehicle movements.
SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.
Gap-Acceptance Capacity: SIDRA Standard (Appelis MSD).
HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement Performance - Pedestrians | | | | | | | | | | | |
|------------------------------------|---------------------|--------|---------|----------|-------------|----------|--------|-----------|--|--|--|
| Mov | Description | Demand | Average | Level of | Average Bac | | Prop. | Effective | | | |
| ID | Description | Flow | Delay | Service | Pedestrian | Distance | Queued | Stop Rate | | | |
| | | ped/h | sec | | ped | m | | per ped | | | |
| P1 | South Full Crossing | 53 | 25.9 | LOS C | 0.1 | 0.1 | 0.59 | 0.59 | | | |
| P2 | East Full Crossing | 53 | 47.3 | LOS E | 0.2 | 0.2 | 0.80 | 0.80 | | | |
| P3 | North Full Crossing | 53 | 25.9 | LOS C | 0.1 | 0.1 | 0.59 | 0.59 | | | |
| P4 | West Full Crossing | 53 | 47.3 | LOS E | 0.2 | 0.2 | 0.80 | 0.80 | | | |
| All Pedestria | ins | 211 | 36.6 | LOS D | | | 0.69 | 0.69 | | | |

Site: Antigue-Brougham-Strickland BASE 2031 PM

Phase times determined by the program Sequence: Split Phasing
Movement Class: All Movement Classes
Input Sequence: A, C
Output Sequence: A, C

| Phase Timing Results | | |
|-------------------------|------|------|
| Phase | Α | С |
| Reference Phase | Yes | No |
| Phase Change Time (sec) | 0 | 59 |
| Green Time (sec) | 53 | 35 |
| Yellow Time (sec) | 4 | 4 |
| All-Red Time (sec) | 2 | 2 |
| Phase Time (sec) | 59 | 41 |
| Phase Split | 59 % | 41 % |





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MOVEMENT SUMMARY

Site: Antigue-Brougham-Strickland BASE 2031 PM

| Movement P | erformance - Vehicles | | | | | | | | | | |
|-----------------|-----------------------|----------------------|-----------------------|---------------------|-------------------------|---------------------|------------------------------------|---------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | De Total veh/h | mand Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Que Vehicles veh | ue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| South: Sricklan | nd | VCIVII | 76 | V/C | 300 | | VOII | | | por von | KIIVII |
| 1 | L2 | 132 | 4.0 | 0.828 | 41.3 | LOS D | 27.6 | 200.0 | 0.98 | 0.94 | 34.3 |
| 2 | T1 | 437 | 4.0 | 0.828 | 36.7 | LOS D | 27.6 | 200.0 | 0.98 | 0.94 | 33.1 |
| 3 | R2 | 7 | 4.0 | 0.094 | 58.9 | LOS E | 0.4 | 2.7 | 1.00 | 0.64 | 28.8 |
| Approach | | 576 | 4.0 | 0.828 | 38.0 | LOS D | 27.6 | 200.0 | 0.98 | 0.94 | 33.3 |
| East: Brougha | m East | | | | | | | | | | |
| 4 | L2 | 214 | 8.0 | 0.233 | 19.0 | LOS B | 5.5 | 41.4 | 0.57 | 0.73 | 42.1 |
| 5 | T1 | 2115 | 8.0 | 1.152 | 194.6 | LOS F | 135.2 | 1010.9 | 1.00 | 2.08 | 14.3 |
| 6 | R2 | 1 | 8.0 | 0.014 | 58.6 | LOS E | 0.1 | 0.4 | 0.99 | 0.57 | 29.0 |
| Approach | | 2329 | 8.0 | 1.152 | 178.5 | LOS F | 135.2 | 1010.9 | 0.96 | 1.96 | 15.2 |
| North: Antigua | | | | | | | | | | | |
| 7 | L2 | 1 | 4.0 | 1.204 | 256.6 | LOS F | 90.3 | 653.9 | 1.00 | 2.33 | 11.5 |
| 8 | T1 | 684 | 4.0 | 1.204 | 252.0 | LOS F | 90.3 | 653.9 | 1.00 | 2.33 | 11.3 |
| 9 | R2 | 139 | 4.0 | 1.183 | 237.1 | LOS F | 17.1 | 123.6 | 1.00 | 1.66 | 12.0 |
| Approach | | 824 | 4.0 | 1.204 | 249.5 | LOS F | 90.3 | 653.9 | 1.00 | 2.22 | 11.4 |
| West: Brougha | am West | | | | | | | | | | |
| 10 | L2 | 140 | 8.0 | 0.154 | 18.4 | LOS B | 3.5 | 25.8 | 0.54 | 0.71 | 42.4 |
| 11 | T1 | 2178 | 8.0 | 1.182 | 219.5 | LOS F | 146.9 | 1098.6 | 1.00 | 2.22 | 13.0 |
| 12 | R2 | 17 | 8.0 | 0.219 | 60.8 | LOS E | 0.9 | 6.5 | 1.00 | 0.68 | 28.5 |
| Approach | | 2335 | 8.0 | 1.182 | 206.3 | LOS F | 146.9 | 1098.6 | 0.97 | 2.12 | 13.7 |
| All ∀ehicles | | 6064 | 7.1 | 1.204 | 185.5 | LOS F | 146.9 | 1098.6 | 0.97 | 1.96 | 14.7 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap-Acceptance Capsachy: SIDRA Standard (Aspetik MSD).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement | Performance - Pedestrians | | | | | | | |
|---------------|---------------------------|--------|---------|----------|-------------|----------|--------|-----------|
| Mov | December 1 | Demand | Average | Level of | Average Bad | | Prop. | Effective |
| ID | Description | Flow | Delay | Service | Pedestrian | Distance | Queued | Stop Rate |
| | | ped/h | sec | | ped | m | | per ped |
| P1 | South Full Crossing | 53 | 21.2 | LOS C | 0.1 | 0.1 | 0.65 | 0.65 |
| P2 | East Full Crossing | 53 | 42.4 | LOS E | 0.1 | 0.1 | 0.92 | 0.92 |
| P3 | North Full Crossing | 53 | 21.2 | LOS C | 0.1 | 0.1 | 0.65 | 0.65 |
| P4 | West Full Crossing | 53 | 42.4 | LOS E | 0.1 | 0.1 | 0.92 | 0.92 |
| All Pedestria | ns | 211 | 31.8 | LOS D | | | 0.79 | 0.79 |

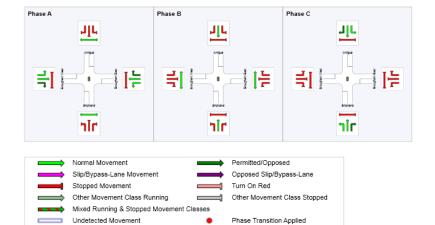
Brougham Street/Strickland Street/Antigua Street

PHASING SUMMARY

Site: Antigue-Brougham-Strickland 2 lane 2031 AM

Phase times determined by the program Sequence: Two-Phase Movement Class: All Movement Classes Input Sequence: A, B, C Output Sequence: A, B, C

Phase Timing Results Reference Phase Phase Change Time (sec) Green Time (sec) Yellow Time (sec) All-Red Time (sec) Phase Time (sec) Phase Split



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MOVEMENT SUMMARY

Site: Antigue-Brougham-Strickland 2 lane 2031 AM

New Site Signals - Fixed Time Isolated Cycle Time = 105 seconds (Optimum Cycle Time - Minimum Delay)

| Movement I | Performance - Vehicles | | | | | | | | | | |
|----------------|------------------------|----------------|------------|--------------|--------------|----------|-----------------|----------|--------|----------------------|--------------------------|
| Mov | OD | Dei | mand Flows | Deg. Satn | Average | Level of | 95% Back of Que | | Prop. | Effective | Average |
| ID | Mov | Total veh/h | HV % | Satn v/c | Delay sec | Service | Vehicles veh | Distance | Queued | Stop Rate per veh | Average Speed km/h |
| South: Srickla | and | venm | 70 | V/C | sec | | ven | m | | per ven | KIII/II |
| 1 | L2 | 144 | 4.0 | 1.253 | 298.9 | LOS F | 111.4 | 806.2 | 1.00 | 2.35 | 10.1 |
| 2 | T1 | 617 | 4.0 | 1.253 | 294.3 | LOS F | 111.4 | 806.2 | 1.00 | 2.35 | 10.0 |
| 3 | R2 | 142 | 4.0 | 1.144 | 204.8 | LOS F | 16.1 | 116.7 | 1.00 | 1.56 | 13.4 |
| Approach | | 903 | 4.0 | 1.253 | 281.0 | LOS F | 111.4 | 806.2 | 1.00 | 2.22 | 10.4 |
| East: Brough: | am East | | | | | | | | | | |
| 4 | L2 | 99 | 8.0 | 0.109 | 19.0 | LOS B | 2.5 | 18.8 | 0.53 | 0.70 | 42.1 |
| 5 | T1 | 2200 | 8.0 | 1.169 | 209.6 | LOS F | 143.7 | 1074.8 | 1.00 | 2.11 | 13.5 |
| 6 | R2 | 1 | 8.0 | 0.014 | 61.4 | LOS E | 0.1 | 0.4 | 0.99 | 0.57 | 28.4 |
| Approach | | 2300 | 8.0 | 1.169 | 201.3 | LOS F | 143.7 | 1074.8 | 0.98 | 2.04 | 13.9 |
| North: Antigua | 8 | | | | | | | | | | |
| 7 | L2 | 1 | 4.0 | 0.377 | 30.7 | LOS C | 9.4 | 67.9 | 0.77 | 0.65 | 38.5 |
| 8 | T1 | 252 | 4.0 | 0.377 | 26.1 | LOS C | 9.4 | 67.9 | 0.77 | 0.65 | 36.9 |
| 9 | R2 | 40 | 4.0 | 0.538 | 64.0 | LOS E | 2.2 | 16.1 | 1.00 | 0.73 | 27.6 |
| Approach | | 293 | 4.0 | 0.538 | 31.3 | LOSC | 9.4 | 67.9 | 0.81 | 0.66 | 35.3 |
| West: Brough | am West | | | | | | | | | | |
| 10 | L2 | 347 | 8.0 | 0.388 | 21.6 | LOS C | 10.5 | 78.8 | 0.64 | 0.77 | 40.9 |
| 11 | T1 | 2125 | 8.0 | 1.247 | 282.0 | LOS F | 174.0 | 1301.5 | 1.00 | 2.45 | 10.7 |
| 12 | R2 | 51 | 8.0 | 0.688 | 66.2 | LOS E | 2.8 | 21.3 | 1.00 | 0.79 | 27.3 |
| Approach | | 2523 | 8.0 | 1.247 | 241.8 | LOS F | 174.0 | 1301.5 | 0.95 | 2.18 | 12.0 |
| All Vehicles | | 6019 | 7.2 | 1.253 | 222.0 | LOS F | 174.0 | 1301.5 | 0.96 | 2.06 | 12.8 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap.-Acceptance Capacity, SIDRA Standard (Aspellik MSD).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

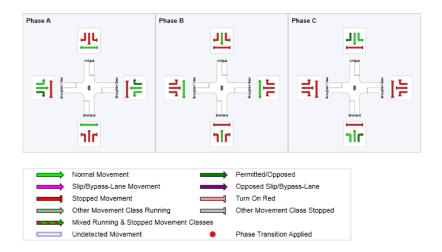
| Movement I | Performance - Pedestrians | | | | | | | |
|----------------|---------------------------|-------------------------|-------------------------|---------------------|----------------------------------|------------------------|-----------------|-----------------------------------|
| Mov ID | Description | Demand Flow ped/h | Average Delay sec | Level of Service | Average Bac Pedestrian ped | k of Queue Distance | Prop. Queued | Effective Stop Rate per ped |
| P1 | South Full Crossing | 53 | 22.1 | LOS C | 0.1 | 0.1 | 0.65 | 0.65 |
| P2 | East Full Crossing | 53 | 46.8 | LOS E | 0.1 | 0.1 | 0.94 | 0.94 |
| P3 | North Full Crossing | 53 | 22.1 | LOS C | 0.1 | 0.1 | 0.65 | 0.65 |
| P4 | West Full Crossing | 53 | 46.8 | LOS E | 0.1 | 0.1 | 0.94 | 0.94 |
| All Pedestrian | ns | 211 | 34.4 | LOS D | | | 0.80 | 0.80 |

Site: Antigue-Brougham-Strickland 2 lane 2031 PM

New Site
Signals - Fixed Time Isolated Cycle Time = 115 seconds (Optimum Cycle Time - Minimum Delay)

Phase times determined by the program Sequence: Two-Phase Movement Class: All Movement Classes Input Sequence: A, B, C Output Sequence: A, B, C

| Phase | Α | В | С |
|-------------------------|------|------|------|
| Reference Phase | Yes | No | No |
| Phase Change Time (sec) | 0 | 69 | 101 |
| Green Time (sec) | 63 | 26 | 8 |
| Yellow Time (sec) | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 |
| Phase Time (sec) | 69 | 32 | 14 |
| Phase Split | 60 % | 28 % | 12 % |



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MOVEMENT SUMMARY

Site: Antigue-Brougham-Strickland 2 lane 2031 PM

| Movement Pe | erformance - Vehicles | | | | | | | | | | |
|------------------|-----------------------|----------------|------------|--------------|--------------|----------|-----------------|---------------|--------|----------------------|---------------|
| Mov | OD | Dei | mand Flows | Deg. Satn | Average | Level of | 95% Back of Que | ue | Prop. | Effective | Average |
| ID | Mov | Total veh/h | HV % | Satn v/c | Delay sec | Service | Vehicles veh | Distance m | Queued | Stop Rate per veh | Speed km/h |
| South: Srickland | d | VG1911 | ~ | 476 | 300 | | ¥611 | | | por von | KIIDII |
| 1 | L2 | 132 | 4.0 | 0.943 | 69.9 | LOS E | 39.8 | 288.2 | 1.00 | 1.13 | 27.1 |
| 2 | T1 | 437 | 4.0 | 0.943 | 65.3 | LOS E | 39.8 | 288.2 | 1.00 | 1.13 | 26.3 |
| 3 | R2 | 7 | 4.0 | 0.108 | 67.5 | LOS E | 0.4 | 3.1 | 1.00 | 0.64 | 26.9 |
| Approach | | 576 | 4.0 | 0.943 | 66.4 | LOS E | 39.8 | 288.2 | 1.00 | 1.12 | 26.5 |
| East: Brougham | n East | | | | | | | | | | |
| 4 | L2 | 214 | 8.0 | 0.226 | 19.8 | LOS B | 6.1 | 45.5 | 0.55 | 0.73 | 41.7 |
| 5 | T1 | 2115 | 8.0 | 1.120 | 172.3 | LOS F | 135.1 | 1010.6 | 1.00 | 1.80 | 15.7 |
| 6 | R2 | 1 | 8.0 | 0.016 | 67.1 | LOS E | 0.1 | 0.5 | 0.99 | 0.57 | 27.2 |
| Approach | | 2329 | 8.0 | 1.120 | 158.3 | LOS F | 135.1 | 1010.6 | 0.96 | 1.70 | 16.6 |
| North: Antigua | | | | | | | | | | | |
| 7 | L2 | 1 | 4.0 | 1.093 | 165.9 | LOS F | 75.1 | 543.5 | 1.00 | 1.70 | 16.0 |
| 8 | T1 | 684 | 4.0 | 1.093 | 161.3 | LOS F | 75.1 | 543.5 | 1.00 | 1.70 | 15.7 |
| 9 | R2 | 139 | 4.0 | 2.052 | 1022.3 | LOS F | 37.8 | 273.8 | 1.00 | 2.33 | 3.4 |
| Approach | | 824 | 4.0 | 2.052 | 306.4 | LOS F | 75.1 | 543.5 | 1.00 | 1.81 | 9.7 |
| West: Broughan | m West | | | | | | | | | | |
| 10 | L2 | 140 | 8.0 | 0.149 | 19.2 | LOS B | 3.8 | 28.4 | 0.52 | 0.71 | 42.1 |
| 11 | T1 | 2178 | 8.0 | 1.147 | 194.4 | LOS F | 146.1 | 1092.8 | 1.00 | 1.92 | 14.3 |
| 12 | R2 | 17 | 8.0 | 0.251 | 69.6 | LOS E | 1.0 | 7.5 | 1.00 | 0.68 | 26.7 |
| Approach | | 2335 | 8.0 | 1.147 | 183.0 | LOS F | 146.1 | 1092.8 | 0.97 | 1.84 | 15.0 |
| All Vehicles | | 6064 | 7.1 | 2.052 | 179.2 | LOS F | 146.1 | 1092.8 | 0.97 | 1.71 | 15.0 |

Level of Service (LOS) Method: Delay (HCM 2000).
Vehicle movement LOS values are based on average delay per movement Intersection and Approach LOS values are based on average delay for all vehicle movements.
SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.
Gap-Acceptance Capacity: SIDRA Standard (Alçelik M3D).
H/ (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement | Performance - Pedestrians | | | | | | | |
|---------------|---------------------------|-------------------------|-------------------------|---------------------|-----------------------------------|-----------------------------|-----------------|-----------------------------------|
| Mov ID | Description | Demand Flow ped/h | Average Delay sec | Level of Service | Average Baci Pedestrian ped | k of Queue Distance m | Prop. Queued | Effective Stop Rate per ped |
| P1 | South Full Crossing | 53 | 21.4 | LOS C | 0.1 | 0.1 | 0.61 | 0.61 |
| P2 | East Full Crossing | 53 | 51.8 | LOS E | 0.2 | 0.2 | 0.95 | 0.95 |
| P3 | North Full Crossing | 53 | 21.4 | LOS C | 0.1 | 0.1 | 0.61 | 0.61 |
| P4 | West Full Crossing | 53 | 51.8 | LOS E | 0.2 | 0.2 | 0.95 | 0.95 |
| All Pedestria | ns | 211 | 36.6 | LOS D | | | 0.78 | 0.78 |

Antigua Street/Disraeli Street

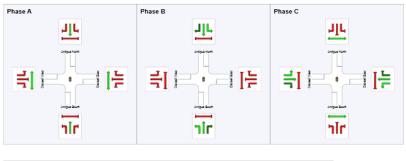
PHASING SUMMARY

Site: Antigua-Disraeli Option 2031 AM

Phase times determined by the program Sequence: Opposed Turns
Movement Class: All Movement Classes
Input Sequence: A, B, C
Output Sequence: A, B, C

Phase Timing Results

| Phase | Α | В | С |
|-------------------------|------|------|------|
| Reference Phase | Yes | No | No |
| Phase Change Time (sec) | 0 | 11 | 23 |
| Green Time (sec) | 5 | 6 | 21 |
| Yellow Time (sec) | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 |
| Phase Time (sec) | 11 | 12 | 27 |
| Phase Split | 22 % | 24 % | 54 % |





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MOVEMENT SUMMARY

Site: Antigua-Disraeli Option 2031 AM

New Site Signals - Fixed Time Isolated Cycle Time = 50 seconds (Optimum Cycle Time - Minimum Delay)

| Movement Per | rformance - Vehicles | | | | | | | | | | |
|-------------------|----------------------|----------------|------------------------|---------------------|-------------------------|---------------------|-------------------------------------|---------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | Total veh/h | emand Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Queu Vehicles veh | Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| South: Antigua S | South | | | | | | • | | | | |
| 1 | L2 | 26 | 12.0 | 0.577 | 19.7 | LOS B | 8.2 | 59.3 | 0.87 | 0.75 | 40.9 |
| 2 | T1 | 371 | 3.4 | 0.577 | 15.0 | LOS B | 8.2 | 59.3 | 0.87 | 0.75 | 41.3 |
| 3 | R2 | 4 | 25.0 | 0.021 | 26.7 | LOS C | 0.1 | 0.8 | 0.90 | 0.63 | 36.1 |
| Approach | | 401 | 4.2 | 0.577 | 15.4 | LOS B | 8.2 | 59.3 | 0.87 | 0.75 | 41.2 |
| East: Disraeli Ea | ist | | | | | | | | | | |
| 4 | L2 | 48 | 6.5 | 0.244 | 14.9 | LOS B | 3.1 | 22.4 | 0.68 | 0.61 | 42.8 |
| 5 | T1 | 143 | 4.4 | 0.244 | 10.3 | LOS B | 3.1 | 22.4 | 0.68 | 0.61 | 43.2 |
| 6 | R2 | 12 | 27.3 | 0.051 | 23.3 | LOS C | 0.2 | 2.1 | 0.83 | 0.67 | 37.4 |
| Approach | | 203 | 6.2 | 0.244 | 12.1 | LOS B | 3.1 | 22.4 | 0.69 | 0.61 | 42.8 |
| North: Antigua N | lorth | | | | | | | | | | |
| 7 | L2 | 31 | 10.3 | 0.293 | 18.0 | LOS B | 3.6 | 27.0 | 0.77 | 0.65 | 41.5 |
| 8 | T1 | 166 | 7.6 | 0.293 | 13.4 | LOS B | 3.6 | 27.0 | 0.77 | 0.65 | 41.9 |
| 9 | R2 | 46 | 9.1 | 0.227 | 27.8 | LOS C | 1.1 | 8.4 | 0.94 | 0.73 | 35.8 |
| Approach | | 243 | 8.2 | 0.293 | 16.7 | LOS B | 3.6 | 27.0 | 0.80 | 0.67 | 40.5 |
| West: Disraeli W | /est | | | | | | | | | | |
| 10 | L2 | 403 | 3.1 | 0.790 | 21.6 | LOS C | 12.2 | 87.4 | 0.86 | 0.91 | 38.7 |
| 11 | T1 | 115 | 2.8 | 0.790 | 17.0 | LOS B | 12.2 | 87.4 | 0.86 | 0.91 | 39.0 |
| 12 | R2 | 118 | 8.9 | 0.249 | 17.3 | LOS B | 2.1 | 15.9 | 0.74 | 0.74 | 40.0 |
| Approach | | 636 | 4.1 | 0.790 | 20.0 | LOS B | 12.2 | 87.4 | 0.84 | 0.88 | 39.0 |
| All Vehicles | | 1483 | 5.1 | 0.790 | 17.1 | LOS B | 12.2 | 87.4 | 0.82 | 0.77 | 40.3 |

Level of Service (i.O.S) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on sverage delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap-Acceptance Capapett; SIDRA Standard (Akpleik Model).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

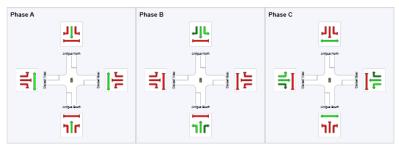
| Movement Per | formance - Pedestrians | | | | | | | |
|-----------------|------------------------|---------------|--------------|----------|-----------------------|----------|--------|----------------------|
| Mov | Description | Demand | Average | Level of | Average Back of Queue | | Prop. | Effective |
| ID | Description | Flow ped/h | Delay sec | Service | Pedestrian ped | Distance | Queued | Stop Rate per ped |
| D4 | South Full Crossing | pedili | 15.2 | LOS B | 0.1 | 0.1 | 0.78 | 0.78 |
| PI | | 53 | | | | | | |
| P2 | East Full Crossing | 53 | 19.4 | LOS B | 0.1 | 0.1 | 0.88 | 0.88 |
| P3 | North Full Crossing | 53 | 15.2 | LOS B | 0.1 | 0.1 | 0.78 | 0.78 |
| P4 | West Full Crossing | 53 | 19.4 | LOS B | 0.1 | 0.1 | 0.88 | 0.88 |
| All Pedestrians | | 211 | 17.3 | LOS B | | | 0.83 | 0.83 |

Site: Antigua-Disraeli Option 2031 PM

Phase times determined by the program Sequence: Opposed Turns Movement Class: All Movement Classes Input Sequence: A, B, C Output Sequence: A, B, C

Phase Timing Results

| Phase | Α | В | С |
|-------------------------|------|------|------|
| Reference Phase | Yes | No | No |
| Phase Change Time (sec) | 0 | 9 | 21 |
| Green Time (sec) | 3 | 6 | 13 |
| Yellow Time (sec) | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 |
| Phase Time (sec) | 9 | 12 | 19 |
| Phase Split | 23 % | 30 % | 48 % |





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MOVEMENT SUMMARY

Site: Antigua-Disraeli Option 2031 PM

New Site
Signals - Fixed Time Isolated Cycle Time = 40 seconds (Optimum Cycle Time - Minimum Delay)

| Movement P | erformance - Vehicles | | | | | | | | | | |
|------------------|-----------------------|----------------|-------------|--------------|--------------|----------|------------------|---------------|--------|----------------------|------------------|
| Mov | OD Mov | D | emand Flows | Deg. Satn | Average | Level of | 95% Back of Queu | | Prop. | Effective | Average Speed |
| ID | Mov | Total veh/h | HV « | Satn v/c | Delay sec | Service | Vehicles veh | Distance m | Queued | Stop Rate per veh | Speed km/h |
| South: Antigua | South | VEIVII | /6 | V/C | 300 | | VCII | | | per veri | KIIVII |
| 1 | L2 | 52 | 4.1 | 0.289 | 14.3 | LOS B | 3.1 | 22.4 | 0.74 | 0.64 | 43.1 |
| 2 | T1 | 169 | 2.5 | 0.289 | 9.7 | LOSA | 3.1 | 22.4 | 0.74 | 0.64 | 43.6 |
| 3 | R2 | 34 | 6.3 | 0.134 | 21.8 | LOS C | 0.6 | 4.5 | 0.90 | 0.71 | 38.1 |
| Approach | | 255 | 3.3 | 0.289 | 12.2 | LOS B | 3.1 | 22.4 | 0.76 | 0.65 | 42.7 |
| East: Disraeli E | ast | | | | | | | | | | |
| 4 | L2 | 21 | 10.0 | 0.413 | 16.5 | LOS B | 4.1 | 29.3 | 0.82 | 0.69 | 42.4 |
| 5 | T1 | 237 | 1.8 | 0.413 | 11.8 | LOS B | 4.1 | 29.3 | 0.82 | 0.69 | 42.9 |
| 6 | R2 | 49 | 6.4 | 0.223 | 23.2 | LOS C | 1.0 | 7.0 | 0.93 | 0.73 | 37.6 |
| Approach | | 307 | 3.1 | 0.413 | 14.0 | LOS B | 4.1 | 29.3 | 0.84 | 0.70 | 41.9 |
| North: Antigua | North | | | | | | | | | | |
| 7 | L2 | 82 | 6.4 | 0.636 | 16.2 | LOS B | 7.9 | 56.7 | 0.87 | 0.77 | 42.3 |
| 8 | T1 | 392 | 1.9 | 0.636 | 11.6 | LOS B | 7.9 | 56.7 | 0.87 | 0.77 | 42.8 |
| 9 | R2 | 132 | 2.4 | 0.472 | 22.9 | LOS C | 2.6 | 18.3 | 0.96 | 0.77 | 37.7 |
| Approach | | 605 | 2.6 | 0.636 | 14.7 | LOS B | 7.9 | 56.7 | 0.89 | 0.77 | 41.5 |
| West: Disraeli | West | | | | | | | | | | |
| 10 | L2 | 159 | 2.6 | 0.851 | 25.2 | LOS C | 10.6 | 75.5 | 0.95 | 1.08 | 38.1 |
| 11 | T1 | 299 | 2.5 | 0.851 | 20.6 | LOS C | 10.6 | 75.5 | 0.95 | 1.08 | 38.4 |
| 12 | R2 | 112 | 4.7 | 0.323 | 19.6 | LOS B | 2.0 | 14.2 | 0.88 | 0.76 | 39.0 |
| Approach | | 569 | 3.0 | 0.851 | 21.7 | LOS C | 10.6 | 75.5 | 0.93 | 1.02 | 38.4 |
| All Vehicles | | 1737 | 2.9 | 0.851 | 16.5 | LOSB | 10.6 | 75.5 | 0.88 | 0.82 | 40.6 |

Level of Service (i,O.S) Method: Delay (HCM 2000).
Vehicle movement LOS values are based on average delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements.
SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.
Gap-Acceptance Capacity: SIDRA Standard (Ayapiik MSD).
HY (S) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement F | Performance - Pedestrians | | | | | | | |
|----------------|---------------------------|----------------|------------------|---------------------|---------------------------|----------|-----------------|------------------------|
| Mov ID | Description | Demand Flow | Average Delay | Level of Service | Average Bac Pedestrian | Distance | Prop. Queued | Effective Stop Rate |
| | | ped/h | sec | | ped | m | | per ped |
| P1 | South Full Crossing | 53 | 14.5 | LOS B | 0.1 | 0.1 | 0.85 | 0.85 |
| P2 | East Full Crossing | 53 | 14.5 | LOS B | 0.1 | 0.1 | 0.85 | 0.85 |
| P3 | North Full Crossing | 53 | 14.5 | LOS B | 0.1 | 0.1 | 0.85 | 0.85 |
| P4 | West Full Crossing | 53 | 14.5 | LOS B | 0.1 | 0.1 | 0.85 | 0.85 |
| All Pedestrian | ns | 211 | 14.5 | LOSB | | | 0.85 | 0.85 |
| | | | | | | | | |

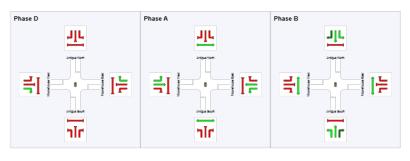
Antigua Street/Moorhouse Avenue base case – no cycleway

PHASING SUMMARY

Site: Antigua - Moorehouse BASE 2031 AM

Phase times determined by the program Sequence: Leading Right Turn Movement Class: All Movement Classes Input Sequence: D, A, B Output Sequence: D, A, B

| Phase Timing Results | | | |
|-------------------------|-------|-------|-------|
| Phase | D | Α | В |
| Reference Phase | No | No | Yes |
| Phase Change Time (sec) | 58 | 70 | 0 |
| Green Time (sec) | 6 | 39 | 52 |
| Yellow Time (sec) | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 |
| Phase Time (sec) | 12 | 45 | 58 |
| Dhace Snlit | 10.94 | 30.96 | 50.96 |





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MOVEMENT SUMMARY

Site: Antigua - Moorehouse BASE 2031 AM

New Site
Signals - Fixed Time Isolated Cycle Time = 115 seconds (Optimum Cycle Time - Minimum Delay)

| Movement F | Performance - Vehicles | | | | | | | | | | |
|----------------|------------------------|----------------|-------------|--------------|--------------|----------|-----------------|---------------|--------|----------------------|------------------|
| Mov | OD Mov | D | emand Flows | Deg. Satn | Average | Level of | 95% Back of Que | ue | Prop. | Effective | Average Speed |
| ID | Mov | Total veh/h | HV % | Satn v/c | Delay sec | Service | Vehicles veh | Distance m | Queued | Stop Rate per veh | Speed km/h |
| South: Antigu | a South | VCIVII | | V/L | 300 | | VCII | "" | | per veri | KIIDII |
| 4 | L2 | 168 | 13.1 | 0.993 | 87.1 | LOS F | 43.3 | 321.2 | 0.86 | 1.19 | 23.3 |
| 5 | T1 | 399 | 4.2 | 0.993 | 82.4 | LOS F | 43.3 | 321.2 | 0.86 | 1.19 | 23.4 |
| 6 | R2 | 224 | 7.0 | 1.219 | 296.4 | LOS F | 32.2 | 239.2 | 1.00 | 1.81 | 9.9 |
| Approach | | 792 | 6.9 | 1.219 | 144.0 | LOS F | 43.3 | 321.2 | 0.90 | 1.36 | 16.9 |
| East: Mooreh | ouse East | | | | | | | | | | |
| 7 | L2 | 5 | 0.0 | 0.009 | 31.0 | LOS C | 0.2 | 1.3 | 0.68 | 0.63 | 34.9 |
| 8 | T1 | 1952 | 7.3 | 1.038 | 115.5 | LOS F | 62.6 | 465.4 | 1.00 | 1.48 | 19.3 |
| 9 | R2 | 14 | 0.0 | 0.141 | 63.8 | LOS E | 0.8 | 5.4 | 0.98 | 0.68 | 26.7 |
| Approach | | 1971 | 7.2 | 1.038 | 114.9 | LOS F | 62.6 | 465.4 | 1.00 | 1.47 | 19.4 |
| North: Antigua | North | | | | | | | | | | |
| 10 | L2 | 37 | 8.6 | 0.048 | 23.2 | LOS C | 1.1 | 8.5 | 0.59 | 0.66 | 37.6 |
| 11 | T1 | 185 | 13.6 | 0.563 | 38.7 | LOS D | 11.2 | 87.0 | 0.91 | 0.78 | 32.6 |
| 12 | R2 | 45 | 9.3 | 0.563 | 43.3 | LOS D | 11.2 | 87.0 | 0.91 | 0.78 | 32.5 |
| Approach | | 267 | 12.2 | 0.563 | 37.3 | LOS D | 11.2 | 87.0 | 0.86 | 0.76 | 33.2 |
| West: Mooreh | ouse West | | | | | | | | | | |
| 1 | L2 | 134 | 4.7 | 0.225 | 33.7 | LOS C | 5.3 | 38.9 | 0.76 | 0.75 | 34.0 |
| 2 | T1 | 2242 | 4.0 | 1.231 | 275.7 | LOS F | 115.3 | 834.4 | 1.00 | 2.25 | 10.5 |
| 3 | R2 | 27 | 7.7 | 0.303 | 65.3 | LOS E | 1.6 | 11.8 | 1.00 | 0.72 | 26.4 |
| Approach | | 2403 | 4.1 | 1.231 | 259.9 | LOS F | 115.3 | 834.4 | 0.99 | 2.15 | 11.0 |
| All Vehicles | | 5433 | 6.0 | 1.231 | 179.5 | LOSF | 115.3 | 834.4 | 0.97 | 1.72 | 14.5 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. Gap-Acceptance Capacity, SIDRA Standard (Askjelik Most.)

| H√ (%) | values | are calc | ulated for | All Movemen | Classes | of All Heavy | Vehicle | Model Designation | ı. |
|--------|--------|----------|------------|-------------|---------|--------------|---------|-------------------|----|
| | | | | | | | | | |

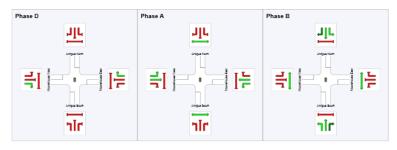
| Movem | ent Performance - Pedestrians | | | | | | | |
|-----------|---|-----|-----------------|-----------------------------------|-----|-----|------|------|
| Mov ID | Demand Average Level of Average Back of Queue Pescription Flow Delay Service Pedestrian Distance pedh sec ped m | | Prop. Queued | Effective Stop Rate per ped | | | | |
| P2 | South Full Crossing | 53 | 35.3 | LOS D | 0.1 | 0.1 | 0.78 | 0.78 |
| P3 | East Full Crossing | 53 | 35.3 | LOS D | 0.1 | 0.1 | 0.78 | 0.78 |
| P4 | North Full Crossing | 53 | 35.3 | LOS D | 0.1 | 0.1 | 0.78 | 0.78 |
| P1 | West Full Crossing | 53 | 35.3 | LOS D | 0.1 | 0.1 | 0.78 | 0.78 |
| All Pede | strians | 211 | 35.3 | LOS D | | | 0.78 | 0.78 |

Site: Antigua - Moorehouse BASE 2031 PM

Phase times determined by the program Sequence: Leading Right Turn Movement Class: All Movement Classes Input Sequence: D, A, B Output Sequence: D, A, B

Phase Timing Results

| Phase | D | Α | В |
|-------------------------|-----|------|-------|
| Reference Phase | No | No | Yes |
| Phase Change Time (sec) | 65 | 77 | 0 |
| Green Time (sec) | 6 | 62 | 59 |
| Yellow Time (sec) | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 |
| Phase Time (sec) | 12 | 68 | 65 |
| Phase Snlit | 8 % | 47 % | 45.96 |





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MOVEMENT SUMMARY

Site: Antigua - Moorehouse BASE 2031 PM

New Site Signals - Fixed Time Isolated Cycle Time = 145 seconds (Optimum Cycle Time - Minimum Delay)

| Mov | OD | D | emand Flows | Deg. | Average | Level of | 95% Back of Que | | Prop. | Effective | Average |
|------------------|----------|----------------|-------------|--------------|--------------|----------|-----------------|---------------|--------|----------------------|-------------|
| | Mov | Total veh/h | HV % | Satin v/c | Delay sec | Service | ∀ehicles veh | Distance m | Queued | Stop Rate per veh | Speed km |
| South: Antigua | South | *01211 | | 1 ,0 | 000 | | 1011 | | | por von | |
| 4 | L2 | 122 | 6.9 | 0.500 | 37.3 | LOS D | 15.4 | 114.9 | 0.77 | 0.71 | 33. |
| 5 | T1 | 186 | 7.9 | 0.500 | 32.7 | LOS C | 15.4 | 114.9 | 0.77 | 0.71 | 34. |
| 6 | R2 | 52 | 8.2 | 0.320 | 65.8 | LOS E | 3.4 | 25.3 | 0.93 | 0.76 | 26. |
| Approach | | 360 | 7.6 | 0.500 | 39.0 | LOS D | 15.4 | 114.9 | 0.79 | 0.72 | 32. |
| East: Moorehou | use East | | | | | | | | | | |
| 7 | L2 | 32 | 3.3 | 0.042 | 30.0 | LOS C | 1.3 | 9.1 | 0.61 | 0.67 | 35. |
| 8 | T1 | 2372 | 3.2 | 0.981 | 83.0 | LOS F | 76.3 | 548.4 | 1.00 | 1.17 | 23. |
| 9 | R2 | 4 | 0.0 | 0.055 | 79.6 | LOS E | 0.3 | 2.1 | 0.98 | 0.64 | 23.5 |
| Approach | | 2407 | 3.1 | 0.981 | 82.3 | LOS F | 76.3 | 548.4 | 0.99 | 1.17 | 23. |
| North: Antigua I | North | | | | | | | | | | |
| 10 | L2 | 42 | 5.0 | 0.059 | 32.1 | LOS C | 1.8 | 12.9 | 0.64 | 0.68 | 34. |
| 11 | T1 | 364 | 4.9 | 1.126 | 203.0 | LOS F | 71.6 | 519.0 | 1.00 | 1.61 | 13.3 |
| 12 | R2 | 161 | 2.6 | 1.126 | 207.5 | LOS F | 71.6 | 519.0 | 1.00 | 1.61 | 13.3 |
| Approach | | 567 | 4.3 | 1.126 | 191.6 | LOS F | 71.6 | 519.0 | 0.97 | 1.54 | 13.5 |
| West: Mooreho | use West | | | | | | | | | | |
| 1 | L2 | 81 | 3.9 | 0.108 | 30.8 | LOS C | 3.4 | 24.4 | 0.63 | 0.70 | 34.9 |
| 2 | T1 | 2612 | 2.4 | 1.118 | 185.6 | LOS F | 121.2 | 865.6 | 1.00 | 1.62 | 14. |
| 3 | R2 | 62 | 5.1 | 0.851 | 90.1 | LOS F | 4.9 | 36.0 | 1.00 | 0.93 | 22.4 |
| Approach | | 2755 | 2.5 | 1.118 | 178.9 | LOS F | 121.2 | 865.6 | 0.99 | 1.58 | 14. |
| All Vehicles | | 6089 | 3.2 | 1.126 | 133.6 | LOS F | 121.2 | 865.6 | 0.98 | 1.36 | 17.7 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements. Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap-Acceptance Capacity, SIDRA Standard (Ajequis MSD).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movemen | t Performance - Pedestrians | | | | | | | |
|--------------|-----------------------------|--------|---------|----------|------------|-------------|--------|-----------|
| Mov | | Demand | Average | Level of | | ck of Queue | Prop. | Effective |
| ID | Description | Flow | Delay | Service | Pedestrian | | Queued | Stop Rate |
| | | ped/h | sec | | ped | l m | | per ped |
| P2 | South Full Crossing | 53 | 32.5 | LOS D | 0.1 | 0.1 | 0.67 | 0.67 |
| P3 | East Full Crossing | 53 | 44.1 | LOS E | 0.2 | 0.2 | 0.78 | 0.78 |
| P4 | North Full Crossing | 53 | 32.5 | LOS D | 0.1 | 0.1 | 0.67 | 0.67 |
| P1 | West Full Crossing | 53 | 44.1 | LOS E | 0.2 | 0.2 | 0.78 | 0.78 |
| All Pedestri | ans | 211 | 38.3 | LOS D | | | 0.73 | 0.73 |

Antigua Street/Moorhouse Avenue

PHASING SUMMARY

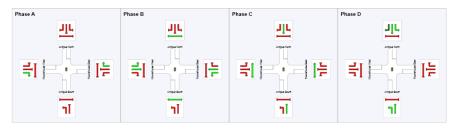
Site: Antigua - Moorehouse 2 Iane OPTION 2031 AM

New Site
Signals - Fixed Time Isolated Cycle Time = 145 seconds (Optimum Cycle Time - Minimum Delay)

Phase times determined by the program Sequence: Leading Right Turn Movement Class: All Movement Classes Input Sequence: A, B, C, D Output Sequence: A, B, C, D

Phase Timing Results

| Phase | Α | В | С | D |
|-------------------------|------|-------|-------|-------|
| Reference Phase | No | Yes | No | No |
| Phase Change Time (sec) | 133 | 0 | 71 | 105 |
| Green Time (sec) | 6 | 65 | 28 | 22 |
| Yellow Time (sec) | 4 | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 | 2 |
| Phase Time (sec) | 12 | 71 | 34 | 28 |
| Dhana Calli | 0.0/ | 40.00 | 22.0/ | 40.00 |





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MOVEMENT SUMMARY

Site: Antigua - Moorehouse 2 Iane OPTION 2031 AM

| | | | | | | | | | - Vehicles | ovement Performance |
|-----------|-----------------------------------|--------------------------------------|--|---|---|--|--|---|--|---|
| ate Speed | Effective Stop Rate per veh | Prop. Queued | k of Queue Distance m | 95% Back Vehicles veh | Level of Service | Average Delay sec | Deg. Satn v/c | Demand Flows HV % | Total veh/h | ov OD Mov |
| | | | | | | | | | | uth: Antigua South |
| .06 21.5 | 1.06 | 1.00 | 111.2 | 14.3 | LOS F | 96.2 | 0.943 | 13.1 | 168 | L2 |
| .73 33.4 | 0.73 | 0.83 | 156.9 | 21.6 | LOS D | 36.7 | 0.731 | 4.2 | 399 | T1 |
| .82 28.7 | 0.82 | 0.88 | 156.9 | 21.6 | LOS D | 54.4 | 0.943 | 6.9 | 567 | proach |
| | | | | | | | | | | st: Moorehouse East |
| .61 36.1 | 0.61 | 0.57 | 1.4 | 0.2 | LOS C | 27.6 | 0.006 | 0.0 | 5 | L2 |
| | 0.83 | 0.92 | 290.5 | 39.1 | LOS D | 36.1 | 0.787 | 7.3 | 1952 | T1 |
| .68 23.7 | 0.68 | 0.99 | 6.9 | 1.0 | LOS F | 81.0 | 0.178 | 0.0 | 14 | R2 |
| .83 33.4 | 0.83 | 0.92 | 290.5 | 39.1 | LOS D | 36.4 | 0.787 | 7.2 | 1971 | proach |
| | | | | | | | | | | rth: Antigua North |
| .68 32.9 | 0.68 | 0.78 | 88.6 | 11.4 | LOS D | 41.3 | 0.409 | 8.6 | 37 | L2 |
| .68 33.2 | 0.68 | 0.78 | 88.6 | 11.4 | LOS D | 36.7 | 0.409 | 13.6 | 185 | T1 |
| .79 23.6 | 0.79 | 1.00 | 25.6 | 3.4 | LOS F | 82.1 | 0.589 | 9.3 | 45 | R2 |
| .70 31.0 | 0.70 | 0.82 | 88.6 | 11.4 | LOS D | 45.0 | 0.589 | 12.2 | 267 | proach |
| | | | | | | | | | | est: Moorehouse West |
| .72 35.2 | 0.72 | 0.63 | 40.3 | 5.5 | LOS C | 29.8 | 0.170 | 4.7 | 134 | L2 |
| .05 27.2 | 1.05 | 0.98 | 468.4 | 64.7 | LOS E | 61.0 | 0.938 | 4.0 | 2242 | T1 |
| .72 23.4 | 0.72 | 1.00 | 15.1 | 2.0 | LOS F | 82.8 | 0.382 | 7.7 | 27 | R2 |
| .03 27.5 | 1.03 | 0.96 | 468.4 | 64.7 | LOS E | 59.5 | 0.938 | 4.1 | 2403 | proach |
| 91 29.8 | 0.91 | 0.93 | 468.4 | 64.7 | LOS D | 49.5 | 0.943 | 6.0 | 5208 | Vehicles |
| 0 1 0 1 | 1 | 1.00 0.82 0.63 0.98 1.00 | 25.6 88.6 40.3 468.4 15.1 468.4 | 3.4 11.4 5.5 64.7 2.0 64.7 | LOS F LOS C LOS E LOS F LOS E | 82.1 45.0 29.8 61.0 82.8 59.5 | 0.589 0.589 0.170 0.938 0.382 0.938 | 9.3 12.2 4.7 4.0 7.7 4.1 | 45 267 134 2242 27 2403 | proach est: Moorehouse West L2 T1 R2 proach |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap-Acceptance Capacity. SIDRA Standard (Akçellik M3D).

HY (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

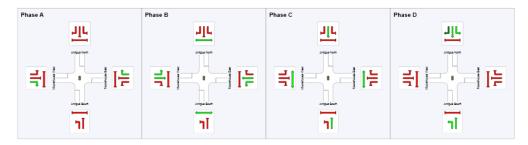
| Movement Pe | rformance - Pedestrians | | | | | | | |
|-----------------|-------------------------|-------------------------|-------------------------|---------------------|----------------------------------|-----|-----------------|-----------------------------------|
| Mov ID | Description | Demand Flow ped/h | Average Delay sec | Level of Service | Average Bac Pedestrian ped | | Prop. Queued | Effective Stop Rate per ped |
| P2 | South Full Crossing | 53 | 30.5 | LOS D | 0.1 | 0.1 | 0.65 | 0.65 |
| P3 | East Full Crossing | 53 | 66.8 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 |
| P4 | North Full Crossing | 53 | 30.5 | LOS D | 0.1 | 0.1 | 0.65 | 0.65 |
| P1 | West Full Crossing | 53 | 66.8 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 |
| All Pedestrians | | 211 | 48.7 | LOS E | | | 0.81 | 0.81 |

Site: Antigua - Moorehouse 2 Iane OPTION 2031 PM

Phase times determined by the program Sequence: Leading Right Turn Movement Class: All Movement Classes Input Sequence: A, B, C, D Output Sequence: A, B, C, D

Phase Timing Results

| Phase | Α | В | С | D |
|-------------------------|-----|------|------|-------|
| Reference Phase | No | Yes | No | No |
| Phase Change Time (sec) | 138 | 0 | 71 | 106 |
| Green Time (sec) | 6 | 65 | 29 | 26 |
| Yellow Time (sec) | 4 | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 | 2 |
| Phase Time (sec) | 12 | 71 | 35 | 32 |
| Phase Snlit | 8 % | 47 % | 23.% | 21.96 |





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MOVEMENT SUMMARY

Site: Antigua - Moorehouse 2 Iane OPTION 2031 PM

New Site Signals - Fixed Time Isolated Cycle Time = 150 seconds (Optimum Cycle Time - Minimum Delay)

| Movement P | erformance - Vehicles | | | | | | | | | | |
|----------------|-----------------------|----------------------|-----------------------|---------------------|-------------------------|---------------------|-------------------------------------|---------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | De Total veh/h | mand Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Quer Vehicles veh | je Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| South: Antigua | South | | | | | | | | | | |
| 4 | L2 | 122 | 6.9 | 0.409 | 64.6 | LOS E | 8.0 | 59.5 | 0.94 | 0.79 | 26.4 |
| 5 | T1 | 186 | 7.9 | 0.246 | 31.0 | LOS C | 8.8 | 66.0 | 0.70 | 0.59 | 35.3 |
| Approach | | 308 | 7.5 | 0.409 | 44.3 | LOS D | 8.8 | 66.0 | 0.79 | 0.67 | 31.2 |
| East: Mooreho | use East | | | | | | | | | | |
| 7 | L2 | 32 | 3.3 | 0.041 | 30.3 | LOS C | 1.3 | 9.3 | 0.60 | 0.67 | 35.1 |
| 8 | T1 | 2372 | 3.2 | 0.968 | 76.9 | LOS E | 74.9 | 538.7 | 1.00 | 1.13 | 24.4 |
| 9 | R2 | 4 | 0.0 | 0.057 | 82.4 | LOS F | 0.3 | 2.2 | 0.98 | 0.64 | 23.5 |
| Approach | | 2407 | 3.1 | 0.968 | 76.3 | LOS E | 74.9 | 538.7 | 0.99 | 1.12 | 24.5 |
| North: Antigua | North | | | | | | | | | | |
| 10 | L2 | 42 | 5.0 | 0.752 | 41.5 | LOS D | 22.4 | 163.2 | 0.82 | 0.72 | 33.0 |
| 11 | T1 | 364 | 4.9 | 0.752 | 36.9 | LOS D | 22.4 | 163.2 | 0.82 | 0.72 | 33.2 |
| 12 | R2 | 161 | 2.6 | 1.131 | 222.1 | LOS F | 22.0 | 157.3 | 1.00 | 1.43 | 12.4 |
| Approach | | 567 | 4.3 | 1.131 | 89.8 | LOS F | 22.4 | 163.2 | 0.87 | 0.92 | 22.6 |
| West: Mooreho | ouse West | | | | | | | | | | |
| 1 | L2 | 81 | 3.9 | 0.106 | 31.2 | LOS C | 3.4 | 24.9 | 0.63 | 0.70 | 34.8 |
| 2 | T1 | 2612 | 2.4 | 1.103 | 175.1 | LOS F | 119.9 | 856.2 | 1.00 | 1.55 | 14.7 |
| 3 | R2 | 62 | 5.1 | 0.880 | 94.9 | LOS F | 5.2 | 37.6 | 1.00 | 0.95 | 21.7 |
| Approach | | 2755 | 2.5 | 1.103 | 169.1 | LOS F | 119.9 | 856.2 | 0.99 | 1.51 | 15.1 |
| All ∀ehicles | | 6038 | 3.2 | 1.131 | 118.2 | LOSF | 119.9 | 856.2 | 0.97 | 1.26 | 19.1 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement Intersection and Approach LOS values are based on average delay for all vehicle movements. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. Gap-Acceptance Capanicly SIDRA Standard (Apkelik MSD).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement Pe | rformance - Pedestrians | | | | | | | |
|-----------------|-------------------------|-------------------------|-------------------------|---------------------|-----------------------------------|---------------------------|-----------------|-----------------------------------|
| Mov ID | Description | Demand Flow ped/h | Average Delay sec | Level of Service | Average Back Pedestrian ped | of Queue Distance m | Prop. Queued | Effective Stop Rate per ped |
| P2 | South Full Crossing | 53 | 32.7 | LOS D | 0.1 | 0.1 | 0.66 | 0.66 |
| P3 | East Full Crossing | 53 | 69.3 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 |
| P4 | North Full Crossing | 53 | 32.7 | LOS D | 0.1 | 0.1 | 0.66 | 0.66 |
| P1 | West Full Crossing | 53 | 69.3 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 |
| All Pedestrians | | 211 | 51.0 | LOS E | | | 0.81 | 0.81 |

Antigua Street/Moorhouse Avenue – allowing full movements (not recommended option)

PHASING SUMMARY

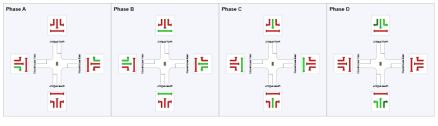
Site: Antigua - Moorehouse 2 Iane OPTION 2031 AM - with RT

New Site
Signals - Fixed Time Isolated Cycle Time = 145 seconds (Optimum Cycle Time - Minimum Delay)

Phase times determined by the program Sequence: Leading Right Turn Movement Class: All Movement Classes Input Sequence: A, B, C, D Output Sequence: A, B, C, D

Phase Timing Results

| riiase iiiiiiiiy kesuiis | | | | |
|--------------------------|------|--------|-------|--------|
| Phase | Α | В | С | D |
| Reference Phase | No | Yes | No | No |
| Phase Change Time (sec) | 133 | 0 | 49 | 83 |
| Green Time (sec) | 6 | 43 | 28 | 44 |
| Yellow Time (sec) | 4 | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 | 2 |
| Phase Time (sec) | 12 | 49 | 34 | 50 |
| Dhone Colit | 0.0/ | 2.4.0/ | 22.0/ | 2.4.0/ |





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MOVEMENT SUMMARY

Site: Antigua - Moorehouse 2 Iane OPTION 2031 AM - with RT

New Site
Signals - Fixed Time Isolated Cycle Time = 145 seconds (Optimum Cycle Time - Minimum Delay)

| Movement | t Performance - Vel | nicles | | | | | | | | | |
|--------------|---------------------|-----------------------|-----------------------|---------------------|-------------------------|---------------------|----------------------------------|-----------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | Den Total veh/h | nand Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Q Vehicles veh | ueue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/h |
| South: Antig | jua South | | | | 300 | | | | | put 1011 | |
| 4 | L2 | 168 | 13.1 | 0.336 | 46.6 | LOS D | 9.2 | 71.6 | 0.82 | 0.78 | 30.3 |
| 5 | T1 | 399 | 4.2 | 1.442 | 487.8 | LOSF | 130.5 | 954.5 | 1.00 | 2.34 | 6.6 |
| 6 | R2 | 224 | 7.0 | 1.442 | 492.3 | LOS F | 130.5 | 954.5 | 1.00 | 2.34 | 6.6 |
| Approach | | 792 | 6.9 | 1.442 | 395.2 | LOS F | 130.5 | 954.5 | 0.96 | 2.01 | 7.9 |
| East: Moore | house East | | | | | | | | | | |
| 7 | L2 | 5 | 0.0 | 0.010 | 42.3 | LOS D | 0.3 | 1.8 | 0.73 | 0.63 | 31.5 |
| 8 | T1 | 1952 | 7.3 | 1.188 | 250.9 | LOS F | 99.7 | 741.4 | 1.00 | 1.86 | 11.3 |
| 9 | R2 | 14 | 0.0 | 0.178 | 81.0 | LOS F | 1.0 | 6.9 | 0.99 | 0.68 | 23.7 |
| Approach | | 1971 | 7.2 | 1.188 | 249.2 | LOS F | 99.7 | 741.4 | 1.00 | 1.85 | 11.3 |
| North: Antig | ua North | | | | | | | | | | |
| 10 | L2 | 37 | 8.6 | 0.234 | 26.0 | LOS C | 8.6 | 67.1 | 0.60 | 0.55 | 38.1 |
| 11 | T1 | 185 | 13.6 | 0.234 | 21.3 | LOS C | 8.6 | 67.1 | 0.60 | 0.55 | 38.5 |
| 12 | R2 | 45 | 9.3 | 0.300 | 64.1 | LOS E | 2.9 | 22.1 | 0.92 | 0.76 | 26.7 |
| Approach | | 267 | 12.2 | 0.300 | 29.2 | LOS C | 8.6 | 67.1 | 0.65 | 0.58 | 35.8 |
| West: Moon | ehouse West | | | | | | | | | | |
| 1 | L2 | 134 | 4.7 | 0.258 | 46.1 | LOS D | 7.1 | 52.0 | 0.80 | 0.76 | 30.5 |
| 2 | T1 | 2242 | 4.0 | 1.410 | 451.0 | LOSF | 158.8 | 1149.9 | 1.00 | 2.46 | 7.0 |
| 3 | R2 | 27 | 7.7 | 0.382 | 82.8 | LOS F | 2.0 | 15.1 | 1.00 | 0.72 | 23.4 |
| Approach | | 2403 | 4.1 | 1.410 | 424.2 | LOS F | 158.8 | 1149.9 | 0.99 | 2.35 | 7.3 |
| All Vehicles | | 5433 | 6.0 | 1.442 | 337.1 | LOS F | 158.8 | 1149.9 | 0.97 | 2.03 | 8.9 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay. Gap-Acceptance Capacity. SIDRA Standard (Akçelik M3D).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

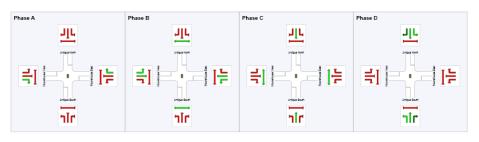
| Moveme | nt Performance - Pedestrians | | | | | | | |
|-----------|------------------------------|--------|---------|----------|-------------|-----|--------|-----------|
| Mov | Di-ti | Demand | Average | Level of | Average Bad | | Prop. | Effective |
| ID | Description | Flow | Delay | Service | Pedestrian | | Queued | Stop Rate |
| | | ped/h | sec | | ped | m | | per ped |
| P2 | South Full Crossing | 53 | 46.5 | LOS E | 0.2 | 0.2 | 0.80 | 0.80 |
| P3 | East Full Crossing | 53 | 66.8 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 |
| P4 | North Full Crossing | 53 | 46.5 | LOS E | 0.2 | 0.2 | 0.80 | 0.80 |
| P1 | West Full Crossing | 53 | 66.8 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 |
| All Pedes | trians | 211 | 56.6 | LOS E | | | 0.88 | 0.88 |

Site: Antigua - Moorehouse 2 Iane OPTION 2031 PM - with RT

New Site
Signals - Fixed Time Isolated Cycle Time = 150 seconds (Optimum Cycle Time - Minimum Delay)

Phase times determined by the program Sequence: Leading Right Turn Movement Class: All Movement Classes Input Sequence: A, B, C, D Output Sequence: A, B, C, D

| Phase | Α | В | С | D |
|-------------------------|-----|------|------|------|
| Reference Phase | No | Yes | No | No |
| Phase Change Time (sec) | 138 | 0 | 71 | 106 |
| Green Time (sec) | 6 | 65 | 29 | 26 |
| Yellow Time (sec) | 4 | 4 | 4 | 4 |
| All-Red Time (sec) | 2 | 2 | 2 | 2 |
| Phase Time (sec) | 12 | 71 | 35 | 32 |
| Phase Split | 8 % | 47 % | 23 % | 21 % |





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MOVEMENT SUMMARY

Site: Antigua - Moorehouse 2 Iane OPTION 2031 PM - with RT

| Movement | t Performance - Ve | phiclos | | | | | | | | | |
|--------------|--------------------|---------|----------------------|---------------------|-------------------------|---------------------|-----------------------------------|----------------------|-----------------|-----------------------------------|--------------------------|
| Mov ID | OD Mov | | and Flows HV % | Deg. Satn v/c | Average Delay sec | Level of Service | 95% Back of Qu Vehicles veh | eue Distance m | Prop. Queued | Effective Stop Rate per veh | Average Speed km/r |
| South: Antig | jua South | | | | | | | | | | |
| 4 | L2 | 122 | 6.9 | 0.409 | 64.6 | LOS E | 8.0 | 59.5 | 0.94 | 0.79 | 26.4 |
| 5 | T1 | 186 | 7.9 | 0.803 | 64.0 | LOS E | 17.2 | 128.4 | 0.97 | 0.92 | 26.9 |
| 6 | R2 | 52 | 8.2 | 0.803 | 68.6 | LOS E | 17.2 | 128.4 | 0.97 | 0.92 | 27.9 |
| Approach | | 360 | 7.6 | 0.803 | 64.9 | LOS E | 17.2 | 128.4 | 0.96 | 0.88 | 26.9 |
| East: Moore | house East | | | | | | | | | | |
| 7 | L2 | 32 | 3.3 | 0.041 | 30.3 | LOS C | 1.3 | 9.3 | 0.60 | 0.67 | 35.1 |
| 8 | T1 | 2372 | 3.2 | 0.968 | 76.9 | LOS E | 74.9 | 538.7 | 1.00 | 1.13 | 24.4 |
| 9 | R2 | 4 | 0.0 | 0.057 | 82.4 | LOS F | 0.3 | 2.2 | 0.98 | 0.64 | 23.5 |
| Approach | | 2407 | 3.1 | 0.968 | 76.3 | LOS E | 74.9 | 538.7 | 0.99 | 1.12 | 24.5 |
| North: Antig | ua North | | | | | | | | | | |
| 10 | L2 | 42 | 5.0 | 0.752 | 41.5 | LOS D | 22.4 | 163.2 | 0.82 | 0.72 | 33.0 |
| 11 | T1 | 364 | 4.9 | 0.752 | 36.9 | LOS D | 22.4 | 163.2 | 0.82 | 0.72 | 33.2 |
| 12 | R2 | 161 | 2.6 | 1.131 | 222.1 | LOS F | 22.0 | 157.3 | 1.00 | 1.43 | 12.4 |
| Approach | | 567 | 4.3 | 1.131 | 89.8 | LOS F | 22.4 | 163.2 | 0.87 | 0.92 | 22.6 |
| West: Moor | ehouse West | | | | | | | | | | |
| 1 | L2 | 81 | 3.9 | 0.106 | 31.2 | LOS C | 3.4 | 24.9 | 0.63 | 0.70 | 34.8 |
| 2 | T1 | 2612 | 2.4 | 1.103 | 175.1 | LOS F | 119.9 | 856.2 | 1.00 | 1.55 | 14.7 |
| 3 | R2 | 62 | 5.1 | 0.880 | 94.9 | LOS F | 5.2 | 37.6 | 1.00 | 0.95 | 21.7 |
| Approach | | 2755 | 2.5 | 1.103 | 169.1 | LOS F | 119.9 | 856.2 | 0.99 | 1.51 | 15.1 |
| All ∀ehicles | | 6089 | 3.2 | 1.131 | 118.8 | LOS F | 119.9 | 856.2 | 0.98 | 1.27 | 19.1 |

Level of Service (LOS) Method: Delay (HCM 2000).

Vehicle movement LOS values are based on average delay per movement intersection and Approach LOS values are based on average delay for all vehicle movements. SIDRA Standard Delay Model is used. Control Delay includes Geometric Delay.

Gap.-Acceptance Capacity: SIDRA Standard (Alx eliki M3D).

HV (%) values are calculated for All Movement Classes of All Heavy Vehicle Model Designation.

| Movement | Performance - Pedestrians | | | | | | | |
|---------------|---------------------------|---------------|--------------|----------|--------------------|---------------|--------|----------------------|
| Mov | Description | Demand | Average | Level of | Average Back of Qu | | Prop. | Effective |
| ID | Description | Flow ped/h | Delay sec | Service | Pedestrian ped | Distance m | Queued | Stop Rate per ped |
| P2 | South Full Crossing | 53 | 32.7 | LOS D | 0.1 | 0.1 | 0.66 | 0.66 |
| P3 | East Full Crossing | 53 | 69.3 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 |
| P4 | North Full Crossing | 53 | 32.7 | LOS D | 0.1 | 0.1 | 0.66 | 0.66 |
| P1 | West Full Crossing | 53 | 69.3 | LOS F | 0.2 | 0.2 | 0.96 | 0.96 |
| All Pedestria | ns | 211 | 51.0 | LOS E | | | 0.81 | 0.81 |